Temposonics
AN AMPHENOL COMPANY

Data Sheet

R-Series V RDV EtherCAT®

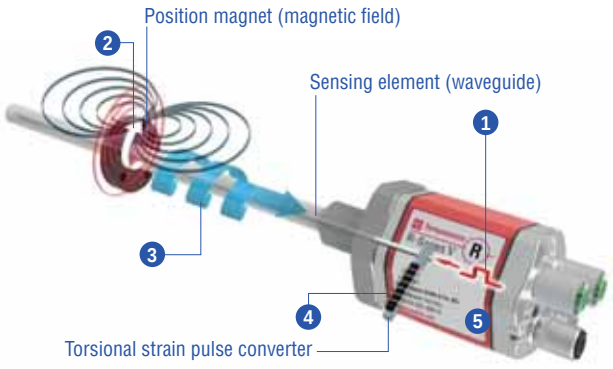
Magnetostrictive Linear Position Sensors

- Space-saving installation due to detached sensor electronics housing
- Backwards compatible with RD4 generation
- All advantages of the R-Series V

THE NEW V GENERATION

MEASURING TECHNOLOGY

The absolute, linear position sensors provided by Temposonics rely on the company's proprietary magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and a supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the beginning of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.



Measurement cycle

1	Current pulse generates magnetic field
2	Interaction with position magnet field generates torsional strain pulse
3	Torsional strain pulse propagates
4	Strain pulse detected by converter
5	Time-of-flight converted into position

Fig. 1: Time-of-flight based magnetostrictive position sensing principle

R-SERIES V RDV EtherCAT®

The Temposonics® R-Series V brings very powerful sensor performance to meet the many demands of your application. The sensor RDV is the version of the R-Series V with a detached sensor electronics. The main advantages of the version RDV are:

Space-saving installation
The detached sensor electronics allow space-saving installation of the compact measuring rod.

R-Series V platform
The detached sensor electronics is based on the R-Series V and offers all advantages of the innovative series.

Backwards compatible
Mechanically and electrically, the sensors are backwards compatible with the RD4. This means that the sensor rod or the sensor electronics can be replaced without any problems.

Protection of the sensor electronics
By separating the robust sensor rod from the complex evaluation electronics, improved protection against process influences can be realized.

In addition the R-Series V EtherCAT® scores with the following features:

30 positions simultaneously
The R-Series V EtherCAT® can detect and report the position, velocity and acceleration of up to 30 magnets simultaneously.

R-Series V EtherCAT®
In addition to the measured position value via the EtherCAT® protocol further data about the current sensor status, such as the total distance travelled, the internal temperature and the total operating hours, can be displayed for diagnostic purposes.

All settings under control with the sensor assistants for the R-Series V
The TempoLink® and the TempoGate® smart assistants support you in setup and diagnostics of the R-Series V. For more information of these assistants please see the data sheets:

- TempoLink® smart assistant (Document part number: 552070)
- TempoGate® smart assistant (Document part number: 552110)

TECHNICAL DATA

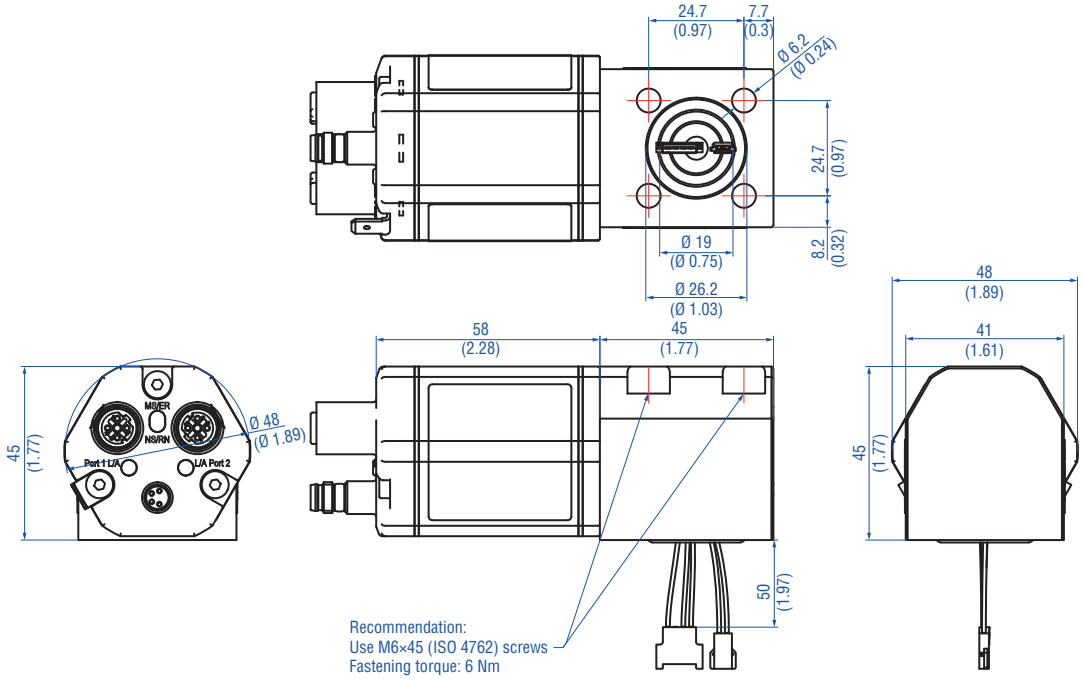
Output	
Interface	EtherCAT® Ethernet Control Automation Technology
Data protocol	EtherCAT® 100 Base-Tx, Fast Ethernet
Data transmission rate	100 MBit/s max.
Measured value	Position, velocity and acceleration/option: Simultaneous multi-position, multi-velocity and multi-acceleration measurements up to 30 magnets
Measurement parameters	
Resolution: Position	0.5…1000 µm (selectable)
Native cycle time	Stroke length: 25 mm | 300 mm | 750 mm | 1000 mm | 2000 mm | 5080 mm Cycle time: 100 µs | 294 µs | 370 µs | 476 µs | 833 µs | 2273 µs
Extrapolation cycle time	Number of magnets: ≤ 10 magnets | 11…30 magnets Cycle time: 100 µs | 250 µs
Linearity deviation [1, 2]	Stroke length: ≤ 500 mm | > 500 mm Linearity deviation: ≤ ±50 µm | < 0.01 % F.S. Optional internal linearity: Linearity tolerance (Applies for the first magnet for multi-position measurement) Stroke length: 25…300 mm | 300…600 mm | 600…1200 mm typical: ±15 µm | ±20 µm | ±25 µm maximum: ±25 µm | ±30 µm | ±50 µm
Repeatability	< ±0.001 % F.S. (minimum ±2.5 µm)
Hysteresis	< 4 µm typical
Temperature coefficient	< 15 ppm/K typical
Operating conditions	
Operating temperature	–40…+85 °C (–40…+185 °F)
Humidity	90 % relative humidity, no condensation
Ingress protection	Sensor electronics IP67 (with professional mounted housing and connectors) Measuring rod with connecting cable for side cable entry IP65 Measuring rod with single wires and flat connector with bottom cable entry IP30
Shock test	100 g/11 ms, IEC standard 60068-2-27
Vibration test	10 g/10…2000 Hz, IEC standard 60068-2-6 (excluding resonant frequencies)
EMC test	Electromagnetic emission according to EN 61000-6-3 Electromagnetic immunity according to EN 61000-6-2 The RDV sensors fulfill the requirements of the EMC directives 2014/30/EU, UKSI 2016 No. 1091 and TR CU 020/2011 under the condition of an EMC-compliant installation. [3]
Operating pressure	350 bar (5076 psi)/700 bar (10,153 psi) peak (at 10 × 1 min) for sensor rod
Magnet movement velocity	Any
Design/Material	
Sensor electronics housing	Aluminum (painted), zinc die cast
Sensor rod with flange	Stainless steel 1.4301 (AISI 304)
RoHS compliance	The used materials are compliant with the requirements of EU Directive 2011/65/EU and EU Regulation 2015/863 as well as UKSI 2022 No. 622
Stroke length	25…2540 mm (1…100 in.) for pressure-fit flange »S« 25…5080 mm (1…200 in.) for all threaded flanges

1/ With position magnet # 251 416-2
2/ For rod style »S« the linearity deviation can be higher in the first 30 mm (1.2 in.) of stroke length
3/ The cable between the sensor element and the electronic housing must be mounted in an appropriately shielded environment.

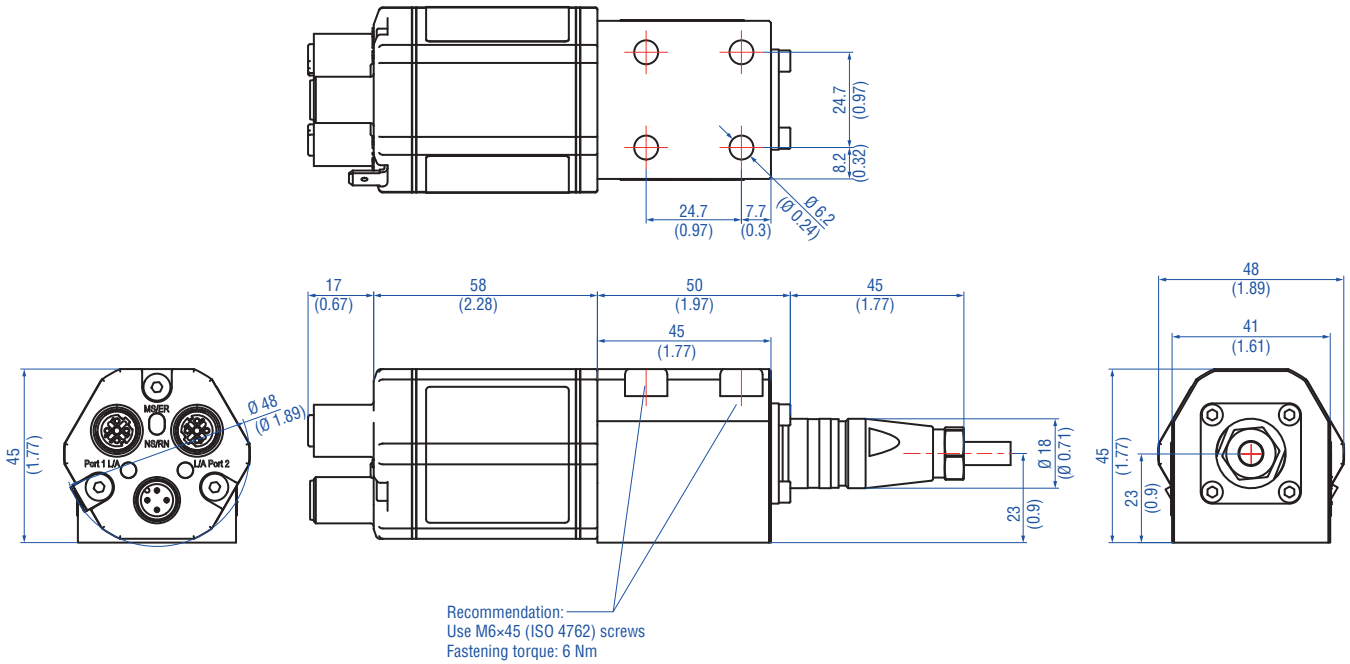
Mechanical mounting	
Mounting position	Any
Mounting instruction	Please consult the technical drawings on page 5 and the operation manual (document number: 552059)
Electrical connection	
Connection type	2 × M12 female connectors (5 pin), 1 × M12 male connector (4 pin) 2 × M12 female connectors (5 pin), 1 × M8 male connector (4 pin)
Operating voltage	+12…30 VDC ±20 % (9.6…36 VDC)
Power consumption	Less than 4 W typical
Dielectric strength	500 VDC (DC ground to machine ground)
Polarity protection	Up to –36 VDC
Overvoltage protection	Up to 36 VDC

TECHNICAL DRAWING

RDV with bottom cable entry, example: Connector D56 (connector outlet)



RDV with side cable entry, example: Connector D58 (connector outlet)

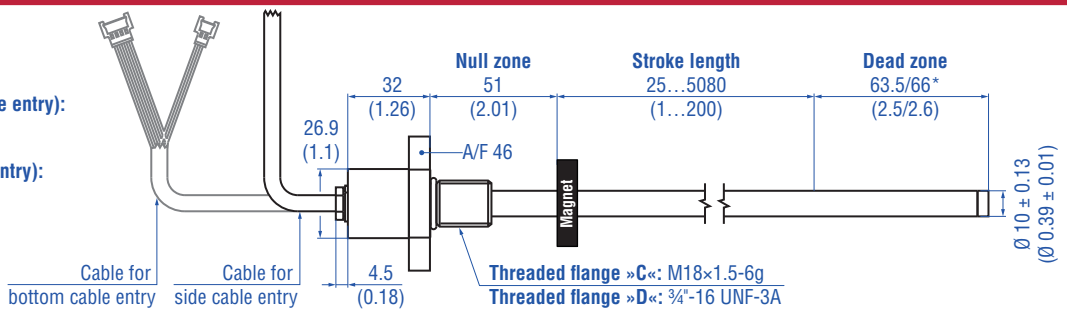


Controlling design dimensions are in millimeters and measurements in ( ) are in inches

Fig. 2: Temposonics® RDV sensor electronics housing

Threaded flange »C« & »D« (for bottom or side cable entry)

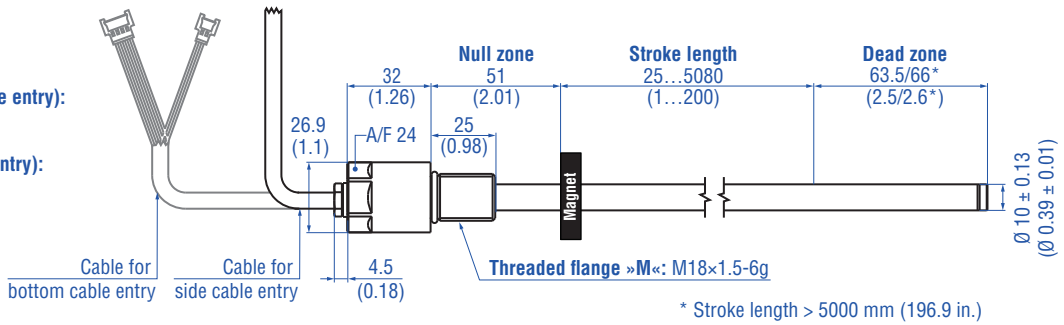
PUR cable:
Ø 6 (Ø 0.24)
Bending radius:
> 24 (> 0.94)
Cable length (bottom cable entry):
65/170/230/350
(2.6/6.7/9.1/13.8)
Cable length (side cable entry):
250/400/600
(9.8/15.7/23.6)



* Stroke length > 5000 mm (196.9 in.)

Threaded flange »M« (for bottom or side cable entry)

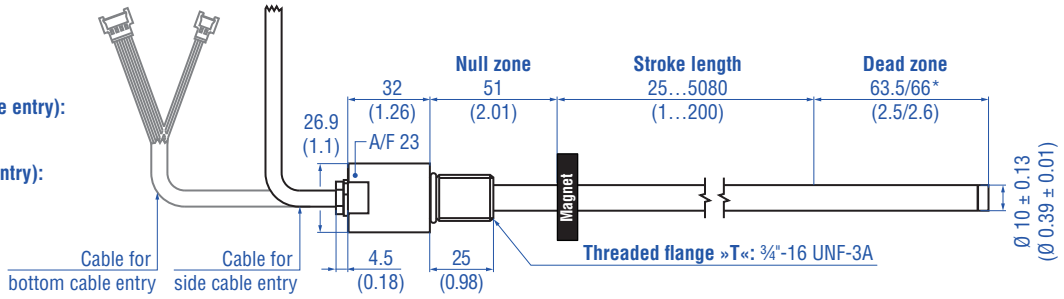
PUR cable:
Ø 6 (Ø 0.24)
Bending radius:
> 24 (> 0.94)
Cable length (bottom cable entry):
65/170/230/350
(2.6/6.7/9.1/13.8)
Cable length (side cable entry):
250/400/600
(9.8/15.7/23.6)



* Stroke length > 5000 mm (196.9 in.)

Threaded flange »T« (for bottom or side cable entry)

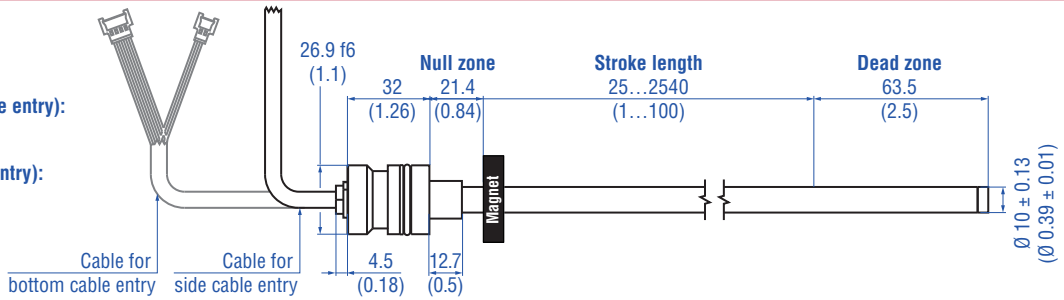
PUR cable:
Ø 6 (Ø 0.24)
Bending radius:
> 24 (> 0.94)
Cable length (bottom cable entry):
65/170/230/350
(2.6/6.7/9.1/13.8)
Cable length (side cable entry):
250/400/600
(9.8/15.7/23.6)



* Stroke length > 5000 mm (196.9 in.)

Pressure fit flange »S« (for bottom or side cable entry)

PUR cable:
Ø 6 (Ø 0.24)
Bending radius:
> 24 (> 0.94)
Cable length (bottom cable entry):
65/170/230/350
(2.6/6.7/9.1/13.8)
Cable length (side cable entry):
250/400/600
(9.8/15.7/23.6)



Controlling design dimensions are in millimeters and measurements in ( ) are in inches

Fig. 3: Temposonics® RDV flange types

CONNECTOR WIRING

D58		
Port 1 – Signal		
M12 female connector (D-coded)	**Pin**	**Function**
 View on sensor	1	Tx (+)
	2	Rx (+)
	3	Tx (–)
	4	Rx (–)
Port 2 – Signal		
M12 female connector (D-coded)	**Pin**	**Function**
 View on sensor	1	Tx (+)
	2	Rx (+)
	3	Tx (–)
	4	Rx (–)
Power supply		
M12 male connector (A-coded)	**Pin**	**Function**
 View on sensor	1	+12…30 VDC (±20 %)
	2	Not connected
	3	DC Ground (0 V)
	4	Not connected

Fig. 4: Connector wiring D58

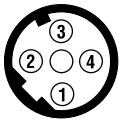
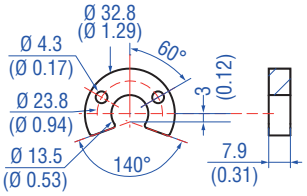
D56		
Port 1 – Signal		
M12 female connector (D-coded)	**Pin**	**Function**
 View on sensor	1	Tx (+)
	2	Rx (+)
	3	Tx (–)
	4	Rx (–)
Port 2 – Signal		
M12 female connector (D-coded)	**Pin**	**Function**
 View on sensor	1	Tx (+)
	2	Rx (+)
	3	Tx (–)
	4	Rx (–)
Power supply		
M8 male connector	**Pin**	**Function**
 View on sensor	1	+12…30 VDC (±20 %)
	2	Not connected
	3	DC Ground (0 V)
	4	Not connected

Fig. 5: Connector wiring D56

FREQUENTLY ORDERED ACCESSORIES – Additional options available in our Accessories Guide 551444

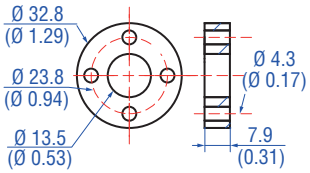
Position magnets



U-magnet OD33
Part no. 251 416-2

Material: PA ferrite GF20
Weight: Approx. 11 g
Surface pressure: Max. 40 N/mm²
Fastening torque for M4 screws: 1 Nm
Operating temperature:
–40…+105 °C (–40…+221 °F)

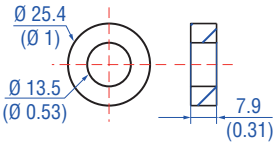
Marked version for sensors with internal linearization: Part no. 254 226



Ring magnet OD33
Part no. 201 542-2

Material: PA ferrite GF20
Weight: Approx. 14 g
Surface pressure: Max. 40 N/mm²
Fastening torque for M4 screws: 1 Nm
Operating temperature:
–40…+105 °C (–40…+221 °F)

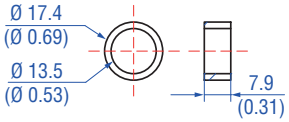
Marked version for sensors with internal linearization: Part no. 253 620



Ring magnet OD25.4
Part no. 400 533

Material: PA ferrite
Weight: Approx. 10 g
Surface pressure: Max. 40 N/mm²
Operating temperature:
–40…+105 °C (–40…+221 °F)

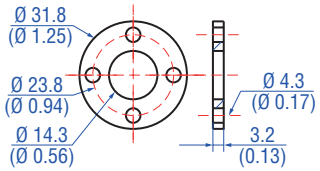
Marked version for sensors with internal linearization: Part no. 253 621



Ring magnet OD17.4
Part no. 401 032

Material: PA neobond
Weight: Approx. 5 g
Surface pressure: Max. 20 N/mm²
Operating temperature:
–40…+105 °C (–40…+221 °F)

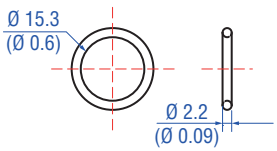
Magnet spacer



Magnet spacer
Part no. 400 633

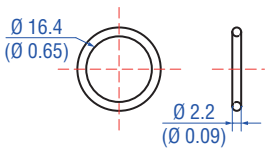
Material: Aluminum
Weight: Approx. 5 g
Surface pressure: Max. 20 N/mm²
Fastening torque for M4 screws: 1 Nm

O-rings



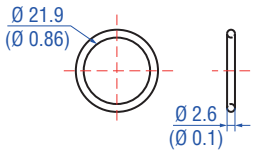
O-ring for threaded flange
M18×1.5-6g
Part no. 401 133

Material: Fluoroelastomer
Durometer: 75 ± 5 Shore A
Operating temperature:
–40…+204 °C (–40…+400 °F)



O-ring for threaded flange
¾"-16 UNF-3A
Part no. 560 315

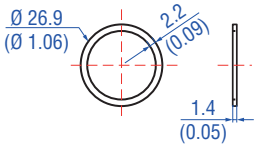
Material: Fluoroelastomer
Durometer: 75 ± 5 Shore A
Operating temperature:
–40…+204 °C (–40…+400 °F)



O-ring for pressure fit flange Ø 26.9 mm
Part no. 560 705

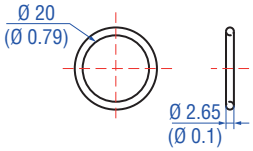
Material: Nitrile rubber
Operating temperature:
–53…+107 °C (–65…+225 °F)

O-rings



Back-up ring for pressure fit flange Ø 26.9 mm
Part no. 560 629

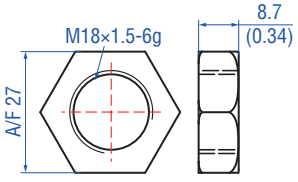
Material: Polymyte
Durometer: 90 Shore A



O-ring for mounting block with bottom entry
Part no. 561 435

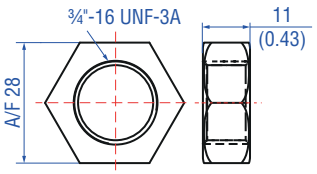
Material: FKM
Durometer: 80± 5 Shore A
Operating temperature:
–15…+200 °C (5…+392 °F)

Mounting accessories



Hex jam nut M18×1.5-6g
Part no. 500 018

Material: Steel, zinc plated

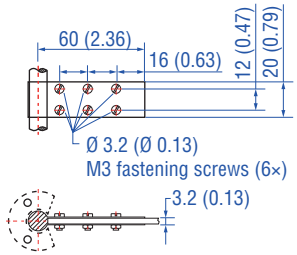


Hex jam nut ¾"-16 UNF-3A
Part no. 500 015

Material: Steel, zinc plated

Controlling design dimensions are in millimeters and measurements in ( ) are in inches

Mounting accessory

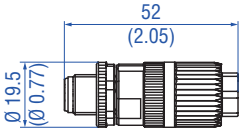


Fixing clip
Part no. 561 481

Application: Used to secure sensor rods (Ø 10 mm (Ø 0.39 in.)) when using an U-magnet or block magnet
Material: Brass, non-magnetic

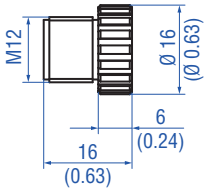
Controlling design dimensions are in millimeters and measurements in ( ) are in inches

Cable connectors* – Signal



M12 D-coded male connector (4 pin), straight
Part no. 370 523

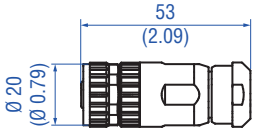
Material: Zinc nickel-plated
Termination: Insulation-displacement
Cable Ø: 5.5…7.2 mm (0.2…0.28 in.)
Wire: 24 AWG – 22 AWG
Operating temperature:
–25…+85 °C (–13…+185 °F)
Ingress protection: IP65 / IP67 (correctly fitted)
Fastening torque: 0.6 Nm



M12 connector end cap
Part no. 370 537

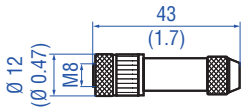
Female connectors M12 should be covered by this protective cap
Material: Brass nickel-plated
Ingress protection: IP67 (correctly fitted)
Fastening torque: 0.39…0.49 Nm

Cable connectors* – Power



M12 A-coded female connector (4 pin/5 pin), straight
Part no. 370 677

Material: GD-Zn, Ni
Termination: Screw
Contact insert: CuZn
Cable Ø: 4…8 mm (0.16…0.31 in.)
Wire: 1.5 mm²
Operating temperature:
–30…+85 °C (–22…+185 °F)
Ingress protection: IP67 (correctly fitted)
Fastening torque: 0.6 Nm



M8 female connector (4 pin), straight
Part no. 370 504

Material: CuZn nickel plated
Termination: Solder
Cable Ø: 3.5…5 mm (0.14…0.28 in.)
Wire: 0.25 mm²
Operating temperature:
–40…+85 °C (–40…+185 °F)
Ingress protection: IP67 (correctly fitted)
Fastening torque: 0.5 Nm

Cables

PUR signal cable
Part no. 530 125

Material: PUR jacket; green
Features: Cat 5, highly flexible, halogen free, suitable for drag chains, mostly oil & flame resistant
Cable Ø: 6.5 mm (0.26 in.)
Cross section: 2 × 2 × 0.35 mm² (22 AWG)
Bending radius: 5 × D (fixed installation)
Operating temperature:
–20…+60 °C (–4…+140 °F)

PVC power cable
Part no. 530 108

Material: PVC jacket; gray
Features: Shielded, flexible, mostly flame resistant
Cable Ø: 4.9 mm (0.19 in.)
Cross section: 3 × 0.34 mm²
Bending radius: 5 × D (fixed installation)
Operating temperature:
–30…+80 °C (–22…+176 °F)

Cable sets

Signal cable with M12 D-coded male connector (4 pin), straight – M12 D-coded, male connector (4 pin), straight
Part no. 530 064

Material: PUR jacket; green
Features: Cat 5e
Cable length: 5 m (16.4 ft)
Cable Ø: 6.5 mm (0.26 in.)
Ingress protection: IP65, IP67, IP68 (correctly fitted)
Operating temperature:
–30…+70 °C (–22…+158 °F)

Signal cable with M12 D-coded male connector (4 pin), straight – RJ45 male connector, straight
Part no. 530 065

Material: PUR jacket; green
Features: Cat 5e
Cable length: 5 m (16.4 ft)
Cable Ø: 6.5 mm (0.26 in.)
Ingress protection M12 connector: IP67 (correctly fitted)
Ingress protection RJ45 connector: IP20 (correctly fitted)
Operating temperature:
–30…+70 °C (–22…+158 °F)

*/ Follow the manufacturer's mounting instructions
Controlling design dimensions are in millimeters and measurements in ( ) are in inches
Color of connectors and cable jacket may change. Colors of the cores and technical properties remain unchanged.

Cable sets		Programming tools	
			
Power cable with M8 female connector (4 pin), straight – pigtail **Part no. 530 066 (5 m (16.4 ft.))** **Part no. 530 096 (10 m (32.8 ft.))** **Part no. 530 093 (15 m (49.2 ft.))**	**Power cable with M12 A-coded female connector (5 pin), straight – pigtail** **Part no. 370 673**	**TempoLink® kit for Temposonics® R-Series V** **Part no. TL-1-0-EM08 (D56)** **Part no. TL-1-0-EM12 (D58)**	**TempoGate® smart assistant for Temposonics® R-Series V** **Part no. TG-C-0-D*xx*** (*xx* indicates the number of R-Serie V sensors that can be connected (even numbers only))
Material: PUR jacket; gray Features: Shielded Cable Ø: 5 mm (0.2 in.) Operating temperature: –40…+90 °C (–40…+194 °F)	Material: PUR jacket; black Features: Shielded Cable length: 5 m (16.4 ft) Ingress protection: IP67 (correctly fitted) Operating temperature: –25…+80 °C (–13…+176 °F)	• Connect wirelessly via Wi-Fi enabled device or via USB with the diagnostic tool • Simple connectivity to the sensor via 24 VDC power line (permissible cable length: 30 m) • User friendly interface for mobile devices and desktop computers • See data sheet “TempoLink® smart assistant” (document part no.: 552070) for further information	• OPC UA server for diagnostics of the R-Series V • For installation in the control cabinet • Connection via LAN and Wi-Fi • See data sheet “TempoGate® smart assistant” document part no.: 552110) for further information

Color of connectors and cable jacket may change. Colors of the cores and technical properties remain unchanged.

ORDER CODE

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
R	D	V										D	5		1	U	1		1
a			b	c	d					e		f			g	h			

a	Design
R D V	Detached sensor electronics “Classic”

b	Design
C	Threaded flange M18×1.5-6g (A/F 46)
D	Threaded flange ¾"-16 UNF-3A (A/F 46)
M	Threaded flange M18×1.5-6g (A/F 24)
S	Pressure fit flange Ø 26.9 mm f6
T	Threaded flange ¾"-16 UNF-3A (A/F 23)

c	Mechanical options
For side cable entry	
A	PUR cable with M16 connector, 250 mm length
B	PUR cable with M16 connector, 400 mm length
C	PUR cable with M16 connector, 600 mm length
For bottom cable entry	
2	Single wires with flat connector, 65 mm length
4	Single wires with flat connector, 170 mm length
5	Single wires with flat connector, 230 mm length
6	Single wires with flat connector, 350 mm length

d	Stroke length
X X X X M	Flange »S«: 0025…2540 mm Flange »C«, »D«, »M«, »T«: 0025…5080 mm

Stroke length (mm)	Ordering steps
25… 500 mm	5 mm
500… 750 mm	10 mm
750…1000 mm	25 mm
1000…2500 mm	50 mm
2500…5080 mm	100 mm

X X X X U	Flange »S«: 001.0…100.0 in. Flange »C«, »D«, »M«, »T«: 001.0…200.0 in.

Stroke length (in.)	Ordering steps
1… 20 in.	0.2 in.
20… 30 in.	0.4 in.
30… 40 in.	1.0 in.
40…100 in.	2.0 in.
100…200 in.	4.0 in.

Non standard stroke lengths are available;
must be encoded in 5 mm/0.1 in. increments

e	Number of magnets
X X	01…30 position(s) (1…30 magnet(s))

f	Connection type
D 5 6	2 × M12 female connectors (D-coded), 1 × M8 male connector
D 5 8	2 × M12 female connectors (D-coded), 1 × M12 male connector (A-coded)

g	System
1	Standard

h	Output
U 1 0 1	EtherCAT®, position, velocity and acceleration (1…30 magnet(s))
U 1 1 1	EtherCAT®, position, velocity and acceleration internal linearization (1…30 magnet(s))

NOTICE

- Specify number of magnets for your application and order the magnets separately.
- The number of magnets is limited by the stroke length. The minimum allowed distance between magnets (i.e. front face of one to the front face of the next one) is 75 mm (3 in.).
- Use magnets of the same type for multi-position measurement.
- If the option for internal linearization (U111) in **h** “Output” is chosen, select a suitable magnet.

DELIVERY

RDV-C/-D/-M/-T:
Sensor, O-ring
RDV-S:
Sensor, O-ring, back-up ring

Accessories have to be ordered separately.

Manuals, Software & 3D Models available at:
www.temposonics.com

GLOSSARY

D

Distributed Clock
EtherCAT® uses a logical network of **D**istributed **C**locks (DC) to synchronize the time on all local bus devices on the network. The EtherCAT® master usually selects the first Distributed Clock capable slave device as a Reference Clock, and then maintains a precise mapping of frame delays for all other slave devices in order to adjust their time to match the system time.

E

ESI
The properties and functions of an EtherCAT® device are described in an ESI file (**E**therCAT® **S**lave **I**nformation). The XML-based ESI file contains all relevant data that are important for the implementation of the device in the controller as well as for data exchange during operation. The ESI file of the R-Series V EtherCAT® is available on the homepage www.temposonics.com.

EtherCAT®
EtherCAT® (**Ether**net for **C**ontrol **A**utomation **T**echnology) is an Industrial Ethernet interface and is managed by the **E**therCAT® **T**echnology **G**roup (ETG). The R-Series V EtherCAT® and its corresponding ESI file are certitified by the ETG.

Extrapolation
The native measurement cycle time of a sensor increases with the stroke length. With extrapolation, the sensor is able to report data faster than the native cycle time, independent of the stroke length of the sensor. Without extrapolation, if data is requested faster than the native cycle time, the last measured value is repeated.

I

Internal Linearization
The internal linearization offers an improved linearity for an overall higher accuracy of the position measurement. The internal linearization is set for the sensor during production.

M

Multi-position measurement
During the measurement cycle, the positions of every magnet on the sensor are simultaneously reported. The velocity and acceleration are continuously calculated based on these changing position values as the magnets are moved.

Temposonics
AN AMPHENOL COMPANY

UNITED STATES
Temposonics, LLC
Americas & APAC Region
3001 Sheldon Drive
Cary, N.C. 27513
Phone: +1 919 677-0100
E-mail: info.us@temposonics.com

GERMANY
Temposonics GmbH & Co. KG
EMEA Region & India
Auf dem Schüffel 9
58513 Lüdenscheid
Phone: +49 2351 9587-0
E-mail: info.de@temposonics.com

ITALY
Branch Office
Phone: +39 030 988 3819
E-mail: info.it@temposonics.com

FRANCE
Branch Office
Phone: +33 6 14 060 728
E-mail: info.fr@temposonics.com

UK
Branch Office
Phone: +44 79 21 83 05 86
E-mail: info.uk@temposonics.com

SCANDINAVIA
Branch Office
Phone: +46 70 29 91 281
E-mail: info.sca@temposonics.com

CHINA
Branch Office
Phone: +86 21 2415 1000 / 2415 1001
E-mail: info.cn@temposonics.com

JAPAN
Branch Office
Phone: +81 3 6416 1063
E-mail: info.jp@temposonics.com

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