NSTALLATION

550571 C

## S P E C I F I C A T I O N S

PARAMETER	SPECIFICATION		
Measured Variable:	Displacement		
Resolution:	1 ÷ [gradient x crystal freq. (mHz) x circulations]		
Non-Linearity*:	$\pm$ 0.02% or $\pm$ 0.05 mm ( $\pm$ 0.002 in.), whichever is greater		
	0.002 in. is the minimum absolute linearity and		
	varies with sensor model		
Repeatability:	Equal to resolution		
Hysteresis:	< 0.02 mm (0.0008 in.)**		
Outputs:	Start/Stop or PWM		
Measuring Range:	25 to 7620 mm (1 to 300 in.)		
Operating Voltage:	+ 13.5 to 26.4 Vdc ( $\pm$ 0%): Strokes $\leq$ 1525 mm (60 in.)		
	+ 24 Vdc (± 10%): Strokes > 1525 mm (60 in.)		
Power Consumption:	100 mA maximum		
Operating Temperature:	Head Electronics: - 40 to 85 °C (- 40 to 185 °F)		
	Sensing Element: - 40 to 105 °C (- 40 to 221 °F)		
EMC Test***:	DIN IEC 801-4, Type 4, CE Qualified; DIN EN 50081-1		
	(Emissions), DIN EN 50082-2 (Immunity)		
Shock Rating:	100 g (single hit)/IEC standard 68-2-27 (survivability)		
Vibration Rating:	5 g/10-150 Hz/IEC standard 68-2-6		

Minimum = [Stroke (specified in inches) + 3] x 9.1 µs			
losure: Sensor Rod: 304L Stainless steel			
Electronic Head: Aluminum die-cast, IP67			
350 bar static, 690 bar spike			
(5,000 psi static, 10,000 psi spike)			
Flange with M18 x 1.5 or 3/4-16 UNF-3A threads			
45 N-m (33 ftlbs.)			
Ring magnet or floating magnet			

All specifications are subject to change. Please contact MTS for specifications critical to your needs.

✤ Non-linearity increases with multiple circulations

₩₩ Power supply dependent.

\*\* \* EMC test specification does not include the sensor with the RB connection style. Sensors with the RB connection style meet the following standard: DIN EN 50081-2 (emisions) and DIN EN 50082-1 (immunity).

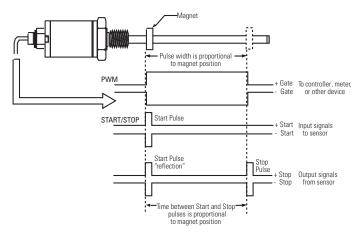
Go to www.mtssensors.com and refer to Product Specification part number  $550658 \ {\rm for}$  additional information.

## **DIGITAL OUTPUTS**

Temposonics L-Series position sensors provide direct Start/Stop amd PWM outputs. The Start/Stop output consists of two differential pairs of signals, (based on the RS-422 standard), that use TTL voltage levels, (0 to 5 volts). One differential pair is used for Start, and the other for Stop. These differential signals provide for better noise immunity.

Each Start/Stop or PWM output style sensor is provided with its actual measured gradient value indicated on the sensor's label. The gradient is the inverse of the rate at which a pulse signal, (generated at the position magnet), propagates through the magnetostrictive waveguide inside the sensor's rod, (about 9 microseconds per inch). As the position magnet is moved further down the sensor rod, more time is required for the pulse signals to travel back to the sensor's electronics at the head. To determine the absolute position of the position magnet it is only necessary to divide the difference in time between the Start signal and the Stop signal by the gradient. The PWM output provides the same elapsed time information, but rather than separate Start and Stop signals, it is represented on one differential pair of signals as a varying pulse width.

For both Start/Stop and PWM standard resolution is 0.004 inches, (when using a 28 MHz counter). Higher resolutions are possible with increased circulations or with the use of higher resolution counters.



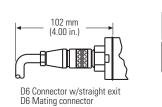
Product specificification is part number 550658.

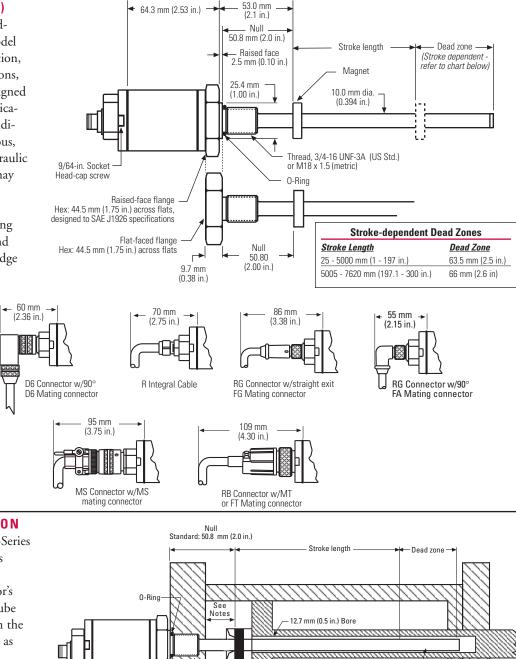
#### DIMENSIONS / T E M P O S O N I C S Model RH

## **ROD-STYLE** (Model RH)

The Temposonics L-Series rodstyle application housing (Model RH) offers modular construction, flexible mounting configurations, and easy installation. It is designed for internal mounting in applications where high-pressure conditions exist (5000 psi continuous, 10,000 psi spike) such as hydraulic cylinders. Temposonics RH may also be mounted externally in many applications.

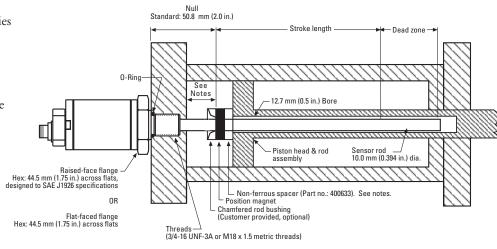
In addition, the RH housing offers the ability to quickly and easily replace the sensor cartridge in the field (up to 72 inches).





## CYLINDER INSTALLATION

The rod-style Temposonics L-Series position sensor (Model LH) is designed for installation into hydraulic cylinders. The sensor's high-pressure, stainless steel tube installs into a 1/2 inch bore in the piston head and rod assembly as shown.



#### NOTES:

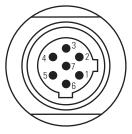
- The position magnet requires minimum distances away from ferrous metals to allow proper sensor output. The minimum distance from the front of the magnet to the cylinder end cap is 15 mm, (0.6 in.). The minimum distance from the back of the magnet to the piston head is provided by the non-ferrous spacer, i.e. 3.2 mm, (0.125 in.).
- The illustration above represents a typical installation. Some installation requirements may be application specific.

## **Integral Connector D6** Integral Cable with Pigtail Termination

Pin No.	Wire Color	Function
1	Gray	(-) Gate for PWM, (-) Stop for Start/Stop
2	Pink	(+) Gate for PWM, (+) Stop for Start/Stop
3	Yellow	(+) Interrogation for PWM,
		(+) Start for Start/Stop
4	Green	(-) Interrogation for PWM,
		(-) Start for Start/Stop
5	Red or Brown	Customer Supplied Power (+ Vdc)*
6	White	DC Ground

(+) Interrogation (see notes 2 & 3 on page 4) (-) Interrogation (see notes 2 & 3 on page 4)

Integral Connector (D6 Male) (As viewed from end of sensor)



**RG** connector (As viewed from end of sensor)

# **RB** Connector: (LH sensors only)

(-) Gate

(+) Gate

Red or Brown Customer supplied power (+ Vdc) ₩ DC ground

No connection

**RG Connector** 

Gray

Pink

Yellow

Green

White

1 2

3

4 5

6

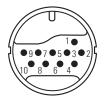
7

Pin no. Wire color Function

Pin no.	Wire color	Function
1	White	DC ground
2	-	No connection
3	Gray	(-) Gate
4	Pink	(+) Gate
5	Red	Customer supplied power (+ Vdc)*
6	-	No connection
7	-	No connection
8	-	No connection
9	Yellow	(+) Interrogation (see notes 2 & 3 on page 4)
10	Green	(-) Interrogation (see notes 2 & 3 on page 4)

\* Power requirements are stroke length dependent.

+13.5 to 26.4 Vdc ( $\pm$  0%) Stroke lengths  $\leq$  1525 mm (60 in.) +24 Vdc (± 10%): Stroke lengths > 1525 mm (60 in.)



**RB** connector (As viewed from end of sensor)

## **MS Connector:**

Pin no.	Wire color	Function
А	White	DC ground
В	-	No connection
С	Gray	(-) Gate
D	Pink	(+) Gate
E	Red	Customer supplied power (+ Vdc)*
F	-	No connection
G	-	No connection
Н	-	No connection
J	Yellow	(+) Interrogation (see notes 2 & 3)
K	Green	(-) Interrogation (see notes 2 & 3)

# R3 Integral Cable with MS Connector:

#### Pin no. Integral cable Function

	wire color	
А	White	DC Ground
В	-	No connection
С	-	No connection
D	Green	(-) Interrogation
E	Yellow	(+) Interrogation
F	-	No connection
G	Pink	(+) Gate
Н	Red	Customer supplied power (+ Vdc)*
J	-	Shield
К	Gray	(-) Gate

\* Power requirements are stroke length dependent.

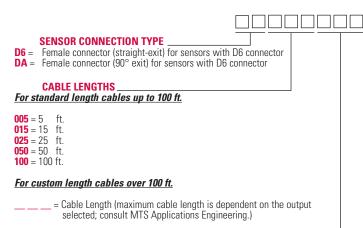
+13.5 to 26.4 Vdc ( $\pm$  0%) Stroke lengths  $\leq$  1525 mm (60 in.)

+24 Vdc (± 10%): Stroke lengths > 1525 mm (60 in.)

### NOTES:

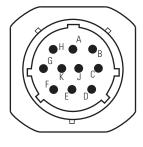
- 1) Appropriate grounding of cable shield is required at the controller end.
- 2) For single-ended interrogation, the unused interrogation lead must be connected to DC ground at the controller.
- 3) When using PWM with internal interrogation, both interrogation leads must be connected to DC ground.

## EXTENSION CABLE WITH CONNECTOR(S) FOR THE D6 CONNECTION TYPE



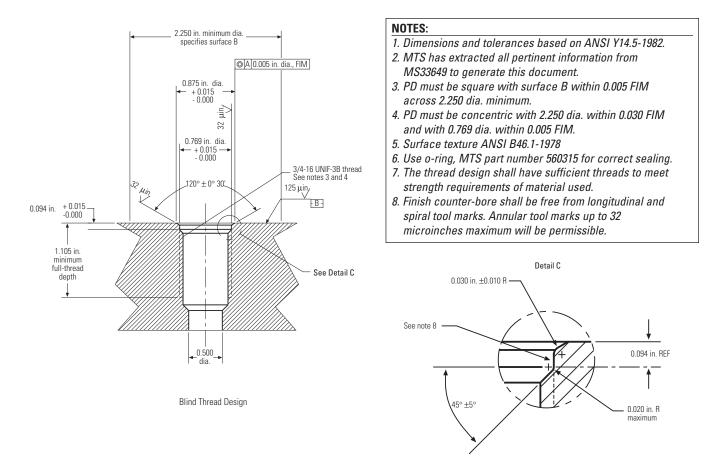
### **CABLE TERMINATION**

**PO** = Pigtail connection **D6M** = 6-pin D6 Male connector (straight exit)

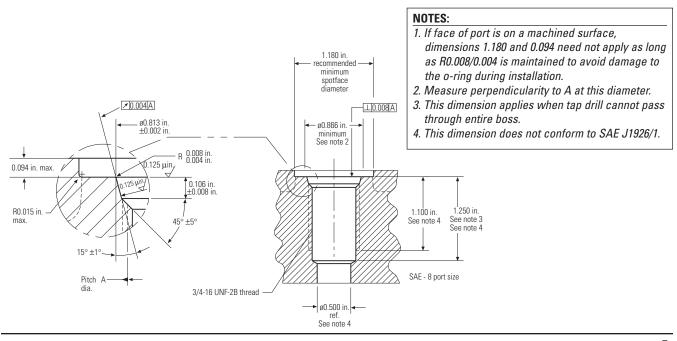


MS connector (As viewed from end of sensor)

## PORT DETAIL (PD) FOR TEMPOSONICS Model RH SENSORS WITH HOUSING STYLE S:



## PORT DETAIL (SAE J1926/1) FOR TEMPOSONICS Model RH SENSORS WITH HOUSING STYLE T:

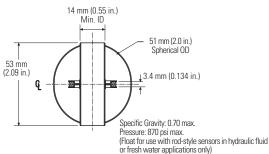


## MAGNETS/FLOAT:

Magnets and floats must be ordered separately with Temposonics LH sensors. A variety of magnet styles (right) are available to meet your particular application needs. The standard ring magnet (Part No. 201542) is suitable for most applications.

(Non-Ferrous spacer for use with standard ring magnet) **Standard Ring Magnet** Part No. 400633 Part No. 201542 . 4 Holes each 3.9 mm O.D. (0.15 in.) 90° apart on 23.9 mm O.D. (0.94 in.)  $\cap$  $\cap$ 4 Holes each 3.9 mm dia. (0.15 in.) 90° apart on 23.9 mm dia. Ć (0.94 in.) ID: 13.5 mm (0.53 in.) OD: 32.8 mm (1.29 in.) Thickness: 7.9 mm (0.312 in.) ID: 14.3 mm (0.563 in.) 0.D.: 31.75 mm (1.25 in.) Thickness: 3.175 mm (0.125 in.) **Ring Magnet Ring Magnet** Part No. 401032 Part No. 400533 ID: 13.5 mm (0.532 in.) ID: 13.5 mm (0.53 in.) 0.D.: 17.4 mm (0.685 in.) 0.D.: 25.4 mm (1.0 in.) Thickness: 7.9 mm (0.312 in.) Thickness: 7.9 mm (0.312 in.) (For use with strokes (For use with strokes  $\leq$  3050 mm or 120 in.)  $\leq$ 1525 mm or 60 in.) **Magnet Float** (Level Sensing Application) **Floating Magnet** Part No. 251447 Part No. 251416 2 Holes each 3.9 mm dia. (0.15 in.) on 23.9 mm dia. (0.94 in.) 14 mm (0.55 in.) Min. ID - 4 25 mm 6 14 mm (0.99 in.) 51 mm (2.0 in.) (0.57 in. ¥ Spherical OD \_20.7 mm (0.81 in.) 13.4 mm (0.134 in.) ID: 13.5 mm (0.53 in.) OD: 32.8 mm (1.29 in.) Thickness: 7.9 mm (0.312 in.) q . Specific Gravity: 0.70 max. Pressure: 870 psi max.

**Magnet Spacer** 



POSITION S	ENSORS		Output code is 2 or 4 digits in length depending on output selected
	г		on output selected
	Ŀ	┥╘┙┝┙╘┥╘┙╘┙╘┙╘╸	
When placing an order,	SENSOR MODEL		
build the desired model	LH = Hydraulic Rod-style		
number using the			
model number guide	HOUSING STYLE T = US customary threads, raised-faced hex, and pressure tube		
(right). A wide range of	<b>S</b> = US customary threads, flat-faced hex, and pressure tube		
0	<ul> <li>M = Metric threads, flat-faced hex, and pressure tube</li> <li>N = Metric threads, raised-faced hex, and pressure tube</li> </ul>		
L-Series sensor	<b>B</b> = Sensor cartridge only, no pressure housing, stroke lengths	≤ 72 in.	
configurations are avail-	CONNECTION TYPE		
able to meet the	D6 = 6-pin DIN, Integral connector		
demands of your partic-	R0 = Integral cable with pigtail terminatiion RG = 7-pin micro connector		
ular application.	<b>RB</b> = 10-pin threaded connector*		
If you have any	MS = 10-pin bayonet-style MS connector R3 = Integral cable with 10-pin male connector (part number 370	160)	
questions about how to	Connection type R3 is for use with L-Series sensors with a	pulse-width modulated	
apply MTS	(PWM) output when retrofitting existing Temposonics digita Contact MTS applications engineering before retrofitti		
Temposonics position			
sensors, please contact	OO = No integral cable		
one of our Application	<b>02</b> = 2 meter integral cable; standard with metric stroke lengths	(i.e., millimeters)	
Engineers or your local	<b>05</b> = 5 ft. integral cable; standard with US customary stroke leng <b>01</b> - <b>99</b> = Custom cable length 1 to 99 ft. (or 1 to 30 meters)	gths (i.e., inches and tenths)	
MTS distributor—they	(Encode length in feet if using US customary stroke length	gth, in meters if using metric stroke length)	
are available to help			
-	CABLE LENGTH NOTES:		
you design an effective	MTS recommends the maximum integral cable len Cables greater than 10 meters in length are availal		
position sensing system	be taken during handling and installation.		
to fit your application.			
	STROKE LENGTH	STROKE LENGTH NOTES: LH sensors with Analog outputs have a stroke	
	U = Inches and tenths (Encode in 0.1 in. increments)	range = $1-100$ in. (25-2540 mm).	
	or M = Millimeters (Encode in 5 mm increments)	LH sensors with Start/Stop or PWM outputs have a stroke range = 1-300 in. (25-7620 mm).	
	INPUT VOLTAGE		
	1 = +13.5 to 26.4 Vdc, (For stroke lengths ≤ 60 inches)		
	<b>2</b> = +24 Vdc, ±10% (For stroke lengths > 60 inches)		
	OUTPUT		
	R0 = Start/Stop		
	$\mathbf{D}_{a} = \frac{1}{b} = \frac{1}{c}$ Pulse-Width Modulated (PWM) (Fill in the three blank	s with the following codes.)	
	a) <u>Interrogation</u> <b>b</b> , c) <u>Circulations</u> <b>b</b> , c) <u>Circulations</u> <b>b</b> , c) <u>Circulations</u> <b>b</b> , c) <u>Circulations</u>	TABLE A:	TABLE B:
	I = Internal (Range = 1 to 15; encode as 01	Circulation Count vs Resolution for PWM Output (Based on 28 MHz counter)	Maximum Circulation Count vs Stroke for PWM Output w/Internal Interrogation
	to 15. Refer to Tables A and B.)	Resolution Circulation Count *	Stroke Maximum Circulation Count
	NOTE:	0.00026 in. (0.0066 mm) 15 0.0005 in. (0.0127 mm) 8	≤ 84 in. (2134 mm) 15 > 84 in. (2136 mm) 1
	Mating connectors, extension cables	0.000 in. (0.0127 mm) 8 0.001 in. (0.025 mm) 4	2 04 III. (2130 IIIII) 1
	and magnets are sold separately	0.002 in (0.051 mm) 2	

and magnets are sold separately.

\* Limited by stroke length for sensors configured for *internal* interrogation. (Refer to Table B)

2

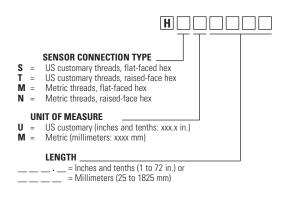
0.002 in. (0.051 mm)

0.004 in. (0.102 mm)

## ACCESSORIES

<u>Description</u>	<u>Part No.</u>	<u>Notes</u>
Magnet spacer	400633	For use with standard ring magnet 201542.
Magnet mounting Screws	560357	Used to mount standard ring magnet Part No. 201542 (4 screws required).
Power supply (24/28 Vdc, 0.5 A)	380009	Open frame style.
LH o-ring (spare)	560315	For sealing LH pressure tube in the cylinder.
Hex-jam nut (w/ 3/4-16 UNF threads)	500015	For US customary stroke lengths.
Hex-jam nut (w/ M18 x 1.5 threads)	500018	For metric stroke lengths.
Collar	560777	For Temposonics LH sensors with float magnet.
Cable	530026	Specify length in feet at time of order.
D6 straight-exit connector	560700	See drawing on page 2.
D6 90° connector	560778	See drawing on page 2.

## PRESSURE HOUSING





## **SENSORS**

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