

Data Sheet

T-Series – TH Analog Magnetostrictive Linear Position Sensors

- ATEX / UK Ex / IECEx / CEC / NEC / EAC Ex / KCs / CCC certified / Japanese approval / **ClassNK** approval
- Continuous operation under harsh industrial conditions
- Flameproof / Explosionproof / Increased safety



MEASURING TECHNOLOGY

The absolute, linear position sensors provided by Temposonics rely on the company's proprietary magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the beginning of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.

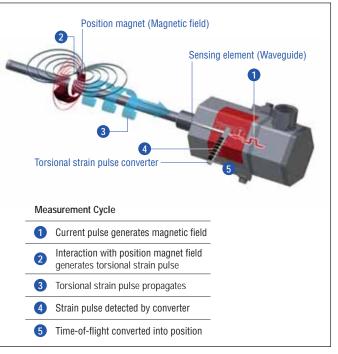


Fig. 1: Time-of-flight based magnetostrictive position sensing principle

TH SENSOR

Robust, non-contact and wear free, the Temposonics[®] linear position sensors provide best durability and accurate position measurement solutions in harsh industrial environments. The position measurement accuracy is tightly controlled by the quality of the waveguide which is manufactured by Temposonics. The position magnet is mounted on the moving machine part and travels contactlessly over the sensor rod with the built-in waveguide.

The TH sensor is extremely robust and ideal for continuous operation under harsh industrial conditions. T-Series sensors are certified for hazardous areas in Zone 0/1, Zone 1, Zone 2, Zone 21 and Zone 22 for Europe (ATEX), the English, Welsh and Scottish (UK Ex), the global (IECEx) market, the Eurasian Economic Union (EAC Ex), the South Korean (KCs), the Chinese (CCC) and the Japanese market, as well as for use in Class I, II, III, Division 1, Division 2 for Canada (CEC) and USA (NEC). The sensor electronics housing contains the active signal conditioning and a complete integrated electronics interface. The sensor rod is capable of withstanding high pressures such as those found in hydraulic cylinders. Furthermore the sensor is also suitable for petro chemical plants and caustic environments. In addition the sensor meets the ingress protection IP66/IP67/IP68 (100 m for 7 days)/ IP69 and NEMA 4 (for sensor assembly in stainless steel 1.4305 (AISI 303)) or NEMA 4x (for sensor assembly in stainless steel 1.4404 (AISI 316L)).



Fig. 2: Typical application: Tank systems

TECHNICAL DATA

Output	
Current	4(0)20 mA, 204(0) mA (minimum/maximum load 0/500 Ω)
Measured value	Position
Measurement parameters	
Resolution	16 bit; 0.0015 % (minimum 1 μm) ¹
Cycle time	0.5 ms up to 1200 mm stroke length
	1.0 ms up to 2400 mm stroke length
	2.0 ms up to 4800 mm stroke length 5.0 ms up to 7620 mm stroke length
Linearity ²	3.6 ms up to 7620 mm stoke length < ±0.01 % F.S. (minimum ±50 μm)
Repeatability	$< \pm 0.001$ % F.S. (minimum ±2.5 µm) typical
Hysteresis	$< 4 \mu m$ typical
Temperature coefficient	< 30 ppm/K typical
Operating conditions	
Operating temperature	-40+75 °C (-40+167 °F)
Humidity	90 % relative humidity, no condensation
Ingress protection	IP66/IP67/IP68 (100 m for 7 days)/IP69 and NEMA 4 (for sensor assembly in stainless steel
° '	1.4305 (AISI 303)) or NEMA 4X (for sensor assembly in stainless steel 1.4404 (AISI 316L))
	(if appropriate pipes, glands, etc. are connected properly)
Shock test	100 g (single shock), IEC standard 60068-2-27
Vibration test	15 g/102000 Hz, IEC standard 60068-2-6 (resonance frequencies excluded)
EMC test	Electromagnetic emission according to IEC/EN 55011 +A1 Class B Electromagnetic immunity according to IEC/EN 61000-6-2
	The sensor meets the requirements of the EU directives and is marked with $C \in$
	The sensor meets the requirements of the UK-legislations and is marked with
Operating pressure	350 bar static (5076 psi static)
Magnet movement velocity ³	Any
Design/Material	
Sensor electronics housing	Stainless steel 1.4305 (AISI 303); option: Stainless steel 1.4404 (AISI 316L)
Flange	See "Table 1: TH rod sensor threaded flange type references" on page 6
Sensor rod	Stainless steel 1.4306 (AISI 304L); option: Stainless steel 1.4404 (AISI 316L)
Stroke length	257620 mm (1300 in.)
Mechanical mounting	
Mounting position	Any
Mounting instruction	Please consult the technical drawings and the operation manual (document number: <u>551513</u>)
Electrical connection	
Connection type	T-Series terminal
Operating voltage	+24 VDC (-15/+20 %)
Ripple	$\leq 0.28 \text{ V}_{pp}$
Current consumption	100 mA typical
Dielectric strength	700 VDC (DC ground to machine ground)
Polarity protection	Up to -30 VDC
Overvoltage protection	Up to 36 VDC

1/ The internal digital value is transferred via a 16 bit D/A converter into a proportional, analog current signal

 $\label{eq:sensor} \begin{array}{l} \textbf{3}/ \ \ \mbox{If there is contact between the moving magnet (including the magnet holder) and the sensor rod, make sure that the maximum speed of the moving magnet is <math display="inline">\leq 1 \ \mbox{m/s}$ (Safety requirement due to ESD [Electro Static Discharge])

CERTIFICATIONS

Certification required	Version E	Version D	Version G	Version N
IECEx/ATEX (IECEx: Global market; ATEX: Europe)	Ex db eb IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 −40 °C ≤ Ta ≤ 75 °C	Ex db IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex db IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C \leq Ta \leq 75 °C	No hazardous area approval
UK Ex (England, Wales and Scotland)	Ex db eb IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 −40 °C ≤ Ta ≤ 75 °C	Ex db IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex db IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C \leq Ta \leq 75 °C	No hazardous area approval
NEC (USA)			$\label{eq:states} \begin{array}{l} \mbox{Explosionproof} \\ \mbox{Class I Div. 1} \\ \mbox{Groups A, B, C, D T4} \\ \mbox{Class II/III Div. 1} \\ \mbox{Groups E, F, G T130°C} \\ \mbox{-40 °C} \leq \mbox{Ta} \leq 75 °C \end{array}$	No hazardous area approval
CEC (Canada)			Explosionproof Class I Div. 1 Groups B, C, D T4 Class II/III Div. 1 Groups E, F, G T130°C -40 °C \leq Ta \leq 75 °C Flameproof Class I Zone 0/1 Ex d IIC T4 Ga/Gb Class II/III Zone 21 Ex tb IIIC T130°C Db -40 °C \leq Ta \leq 75 °C	No hazardous area approval
EAC Ex (Eurasian Economic Union)	Ga/Gb Ex db eb IIC T4 X Ex tb IIIC T130°C Db X Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ga/Gb Ex db IIC T4 X Ex tb IIIC T130°C Db X Zone 0/1, Zone 21 −40 °C ≤ Ta ≤ 75 °C	Ga/Gb Ex db IIC T4 X Ex tb IIIC T130°C Db X Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	No hazardous area approval
KCs (South Korea)	Ex d e IIC T4 Ex tb IIIC T130°C Zone 0/1; Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex d IIC T4 Ex tb IIIC T130°C Zone 0/1; Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex d IIC T4 Ex tb IIIC T130°C Zone 0/1; Zone 21 -40 °C ≤ Ta ≤ 75 °C	No hazardous area approval
Japanese approval	Ex d e IIC T4 Ga/Gb Ex t IIIC T130°C Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex d IIC T4 Ga/Gb Ex t IIIC T130°C Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex d IIC T4 Ga/Gb Ex t IIIC T130°C Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	No hazardous area approval
CCC (China)	Ex d e IIC T4 Gb Ex tD A21 IP66/67 T130°C Zone 1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex d IIC T4 Gb Ex tD A21 IP66/67 T130°C Zone 1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex d IIC T4 Gb Ex tD A21 IP66/67 T130°C Zone 1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	No hazardous area approval

Fig. 3: Certifications

TECHNICAL DRAWINGS

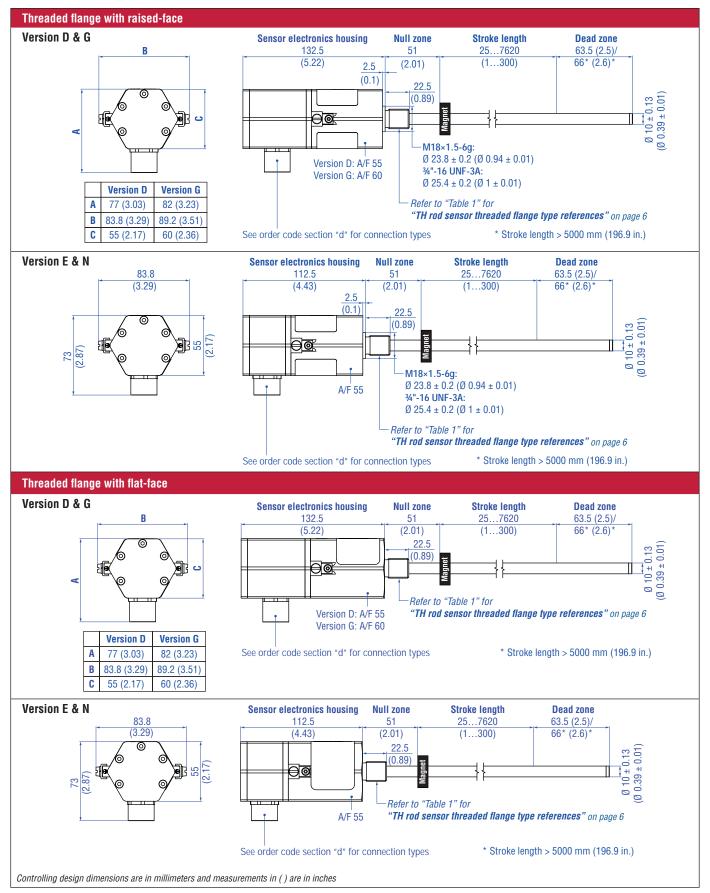


Fig. 4: Temposonics® TH with ring magnet

CONNECTION OPTIONS

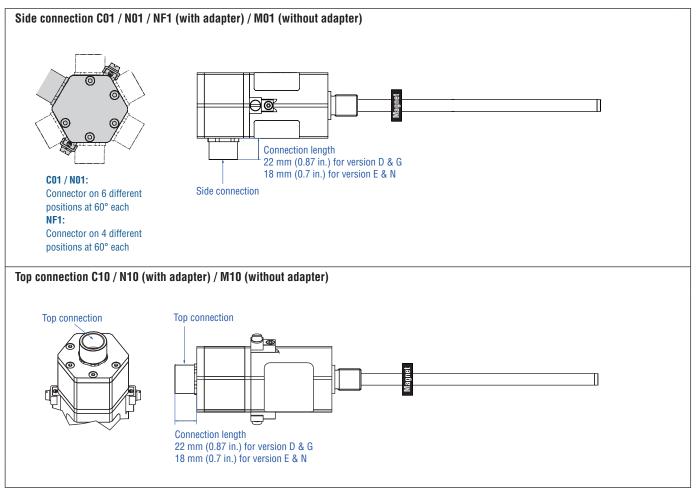


Fig. 5: Temposonics® TH connection options

Threaded flange type	Description	Threaded flange
F	Threaded flange with flat-face Stainless steel 1.4404 (AISI 316L)	3⁄4"-16 UNF-3A
G	Threaded flange with raised-face Stainless steel 1.4404 (AISI 316L)	3⁄4"-16 UNF-3A
М	Threaded flange with flat-face Stainless steel 1.4305 (AISI 303)	M18×1.5-6g
N	Threaded flange with raised-face Stainless steel 1.4305 (AISI 303)	M18×1.5-6g
S	Threaded flange with flat-face Stainless steel 1.4305 (AISI 303)	3⁄4"-16 UNF-3A
т	Threaded flange with raised-face Stainless steel 1.4305 (AISI 303)	3⁄4"-16 UNF-3A
W	Threaded flange with flat-face Stainless steel 1.4404 (AISI 316L)	M18×1.5-6g

Table 1: TH rod sensor threaded flange type references

ZONE CLASSIFICATION

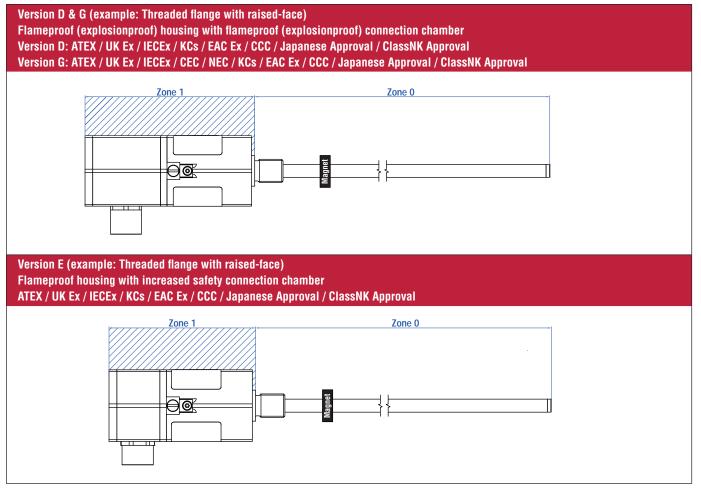


Fig. 6: Temposonics® TH Zone classification

NOTICE

Seal sensor according to ingress protection IP67 between Zone 0 and Zone 1.

CONNECTOR WIRING

Version D & G suitable for connection types: C01, C10, N01, N10					
Signal + power si	Signal + power supply				
Terminal		Pin	Function		
		1	Output 1		
		2	Signal Ground		
		3	Output 2		
		4	Signal Ground		
v		5	+24 VDC (-15/+20 %)		
6		6	DC Ground (0 V)		
		7	Cable shield		

Fig. 7: TH (version D & G) wiring diagram (2.5 mm² conductor)

Version E & N suitable for connection types: C01, C10, M01, M10, N01, N10				
Signal + power supply				
Terminal	Pin	Function		
	1	Output 1		
	2	Signal Ground		
	3	Output 2		
	4	Signal Ground		
	5	+24 VDC (-15/+20 %)		
	6	DC Ground (0 V)		
	7	Cable shield		

Fig. 8: TH (version E & N) wiring diagram (1.5 mm² conductor)

Version E & N suitable for connection type: NF1				
Signal + power supply				
Terminal Pin Function				
	1	Output 1		
	2	Signal Ground		
	3	Output 2		
4 00	4	+24 VDC (-15/+20 %)		
	5	DC Ground (0 V)		
	6	Cable shield		

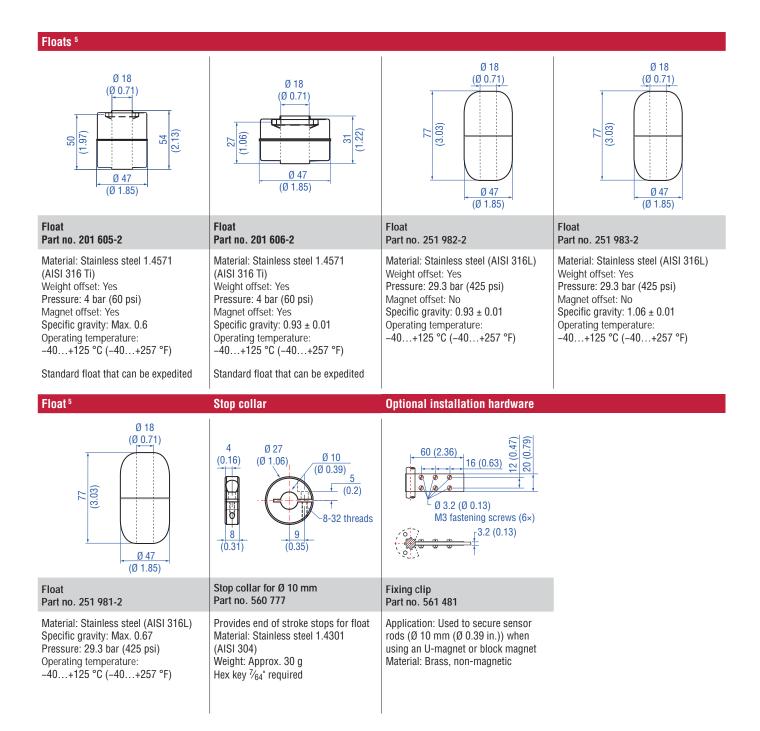
Fig. 9: TH (version E & N) wiring diagram (2.5 mm² conductor)

FREQUENTLY ORDERED ACCESSORIES – Additional options available in our Accessories Guide [] 551444

Position magnete			
$ \begin{array}{c} \underline{\emptyset \ 32.8} \\ (\underline{\emptyset \ 1.29}) \\ \underline{\emptyset \ 23.8} \\ (\underline{\emptyset \ 0.94}) \\ \underline{\emptyset \ 13.5} \\ (\underline{\emptyset \ 0.53}) \\ \end{array} $	<u>Ø 25.4</u> (Ø 1) <u>Ø 13.5</u> (Ø 0.53) <u>7.9</u> (0.31)	$\begin{array}{c} 0 & 32.8 \\ \hline 0 & 4.3 \\ \hline (0 & 0.17) \\ \hline 0 & 23.8 \\ \hline 0 & 0.94 \\ \hline 0 & 13.5 \\ \hline (0 & 0.53) \\ \end{array}$	Ø 63.5 (Ø 2.5) Ø 42 Ø 1.65) Ø 16 (Ø 0.63) Ø 7° Ø 4.5 (Ø 0.18) Ø 5 (0.37)
Ring magnet OD33 Part no. 201 542-2	Ring magnet OD25.4 Part no. 400 533	U-magnet OD33 Part no. 251 416-2	U-magnet OD63.5 Part no. 201 553
Material: PA ferrite GF20 Weight: Approx. 14 g Surface pressure: Max. 40 N/mm ² Fastening torque for M4 screws: 1 Nm Operating temperature: -40+105 °C (-40+221 °F)	Material: PA ferrite Weight: Approx. 10 g Surface pressure: Max. 40 N/mm ² Operating temperature: -40+105 °C (-40+221 °F)	Material: PA ferrite GF20 Weight: Approx. 11 g Surface pressure: Max. 40 N/mm ² Fastening torque for M4 screws: 1 Nm Operating temperature: -40+105 °C (-40+221 °F)	Material: PA 66-GF30, magnets compound-filled Weight: Approx. 26 g Surface pressure: 20 N/mm ² Fastening torque for M4 screws: 1 Nm Operating temperature: -40+75 °C (-40+167 °F)
Magnet spacer	Floats ⁴		
$ \begin{array}{c} $	Ø 18 (Ø 0.71) (Ø 0.72) (Ø 0.72	Ø 18 (Ø 0.71) (Ø 0.71	Ø 18 (Ø 0.71) 5 (Ø 0.71) (Ø 0.
Magnet spacer Part no. 400 633	Float Part no. 251 387-2	Float Part no. 200 938-2	Float Part no. 251 469-2
Material: Aluminum Weight: Approx. 5 g Surface pressure: Max. 20 N/mm ² Fastening torque for M4 screws: 1 Nm	Material: Stainless steel (AISI 316L) Weight offset: Yes Pressure: 22.4 bar (325 psi) Magnet offset: No Specific gravity: Max. 0.48 Operating temperature: -40+125 °C (-40+257 °F)	Material: Stainless steel (AISI 316L) Weight offset: Yes Pressure: 8.6 bar (125 psi) Magnet offset: No Specific gravity: Max. 0.74 Operating temperature: -40+125 °C (-40+257 °F)	Material: Stainless steel (AISI 316L) Weight offset: Yes Pressure: 29.3 bar (425 psi) Magnet offset: No Specific gravity: Max. 0.45 Operating temperature: -40+125 °C (-40+257 °F)

Controlling design dimensions are in millimeters and measurements in () are in inches

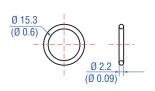
- 4/ Be sure that the float specific gravity is at least 0.05 less than that of the measured liquid as a safety margin at ambient temperature
 For interface measurement: A minimum of 0.05 specific gravity differential is required between the upper and lower liquids
 When the magnet is not shown, the magnet is positioned at the center line of float
- An offset weight is installed in the float to bias or tilt the float installed on the sensor tube. So the float remains in contact with the sensor tube at all times and guarantees permanent potential equalization of the float. The offset is required for installations that must conform to hazardous location standards



Controlling design dimensions are in millimeters and measurements in () are in inches

- 5/ Be sure that the float specific gravity is at least 0.05 less than that of the measured liquid as a safety margin at ambient temperature
 - For interface measurement: A minimum of 0.05 specific gravity differential is required between the upper and lower liquids
 - . When the magnet is not shown, the magnet is positioned at the center line of float
- An offset weight is installed in the float to bias or tilt the float installed on the sensor tube. So the float remains in contact with the sensor tube at all times and guarantees permanent potential equalization of the float. The offset is required for installations that must conform to hazardous location standards

O-rings



O-ring for threaded flange M18×1.5-6g Part no. 401 133

Material: Fluoroelastomer Durometer: 75 ± 5 Shore A Operating temperature: -40...+204 °C (-40...+400 °F)

Programming tools





Ø 2.2

(Ø 0.09)

Hand programmer for analog output Part no. 253 124

Easy teach-in-setups of stroke length and direction on desired zero/span positions. For sensors with 1 magnet.

- Programming kit Part no. 253 134-1
- Kit includes:

Ø 16.4

(Ø 0.65)

34"-16 UNF-3A

Part no. 560 315

O-ring for threaded flange

Material: Fluoroelastomer

Operating temperature:

Durometer: 75 ± 5 Shore A

-40...+204 °C (-40...+400 °F)

- $1 \times interface$ converter box,
- 1 × power supply 1 × cable (60 cm) with M16 female
- connector (6 pin), straight D-sub female connector (9 pin), straight 1 × cable (60 cm) with 3 × terminal clamp – D-sub female connector
- (9 pin), straight 1 × USB cable

For sensors with 1 or 2 magnets.

Software is available at: www.temposonics.com



Cabinet programmer for analog output Part no. 253 408

Features snap-in mounting on standard DIN rail (35 mm). This programmer can be permanently mounted in a control cabinet and includes a program/run switch. For sensors with 1 magnet.

Controlling design dimensions are in millimeters and measurements in () are in inches

ORDER CODE

1 2 3 4 5 6 7 8 9 10 11 12 T H b c d e	13 14 15 16 17 18 N N Image: Second secon
a Sensor model	d Connection type
T H Rod	C O 1 Side connection with thread ½"-14 NPT (All versions)
b Design	C 1 0 Top connection with thread ½"-14 NPT
Enclosure Type 4:	(All versions)
TH rod sensor with housing material stainless steel 1.4305 (AISI 303) and rod material stainless steel 1.4306 (AISI 304L)	M 0 1 Side connection with thread M16×1.5-6H (Version E & N)
M Threaded flange with flat-face (M18×1.5-6g)	M 1 0 Top connection with thread M16×1.5-6H
N Threaded flange with raised-face (M18×1.5-6g)	(Version E & N)
S Threaded flange with flat-face (34"-16 UNF-3A)	N 0 1 Side connection with thread M20×1.5-6H
T Threaded flange with raised-face (3/4"-16 UNF-3A)	(All versions)
Enclosure Type 4X: TH rod sensor with housing material stainless steel 1.4404	N 1 0 Top connection with thread M20×1.5-6H (All versions)
(AISI 316L) and rod material stainless steel 1.4404 (AISI 316L)	N F 1 Side connection with thread M20×1.5-6H
F Threaded flange with flat-face (3/4"-16 UNF-3A)	(Version E & N)
G Threaded flange with raised-face (3/4"-16 UNF-3A)	
W Threaded flange with flat-face (M18×1.5-6g)	e Operating voltage
	1 +24 VDC (-15 / +20 %)
c Stroke length	1 Annal and a second
X X X X M 00257620 mm	f Version (see "Certifications" on page 4 for further information)
Standard stroke length (mm) Ordering steps	
25 500 mm 5 mm	
500 750 mm 10 mm	E Ex db eb and Ex tb (A/F 55) C Ex db and Ex tb (A/F 60)

25 mm

50 mm

100 mm

250 mm

0.2 in.

0.4 in.

1.0 in.

2.0 in.

4.0 in.

10.0 in.

Ordering steps

- G Ex db and Ex tb (A/F 60) US & CA approval: Explosionproof (XP)
 - (Note: Group A is not available for Canada)
- Ν Not approved

g See next page

Non Standard stroke lengths are available;

X X X X U 001.0...300.0 in.

Standard stroke length (in.)

750...1000 mm

1000...2500 mm

2500...5000 mm

5000...7620 mm

1 ... 20 in.

20 ... 30 in.

30 ... 40 in.

40...100 in.

100...200 in.

200...300 in.

must be encoded in 5 mm/0.1 in. increments.

121

g	Functional safety type				
Ν	Not	Not approved			
_					
h	Ado	litio	nal option type		
K	Cla	ssNI	K approval		
	(No	tice	: Available with the following configurations		
	C	Str	oke length: 25500 mm (standard)		
	f	Vei	rsion: D, E, G)		
Ν	Nor	ne			
i	Output				
1 0	outpu	ıt wi	th 1 position magnet		
Ou	tput	1 (p	osition magnet 1)		
Α	0	1	420 mA		
Α	1	1	204 mA		
A A	1 2	1 1	204 mA 020 mA		
	Ŀ	<u> </u>			

Output 1 (position magnet 1) + output 2 (position magnet 1)

 A
 0
 3
 4...20 mA
 20...4 mA

2 outputs with 2 position magnets Output 1 (position magnet 1) + output 2 (position magnet 2)					
A	0	2	420 mA	420 mA	
A	1	2	204 mA	204 mA	
A	2	2	020 mA	020 mA	
A	3	2	200 mA	200 mA	

NOTICE

- Specify magnet numbers for your sensing application and order separately.
- The number of magnets is limited by the stroke length.
- The minimum allowed distance between magnets (i.e. front face of one to the front face of the next one) is 75 mm (3 in.).
- Use magnets of the same type for multi-position measurement, e.g. 2 ring magnets (part no. 201 542-2).

DELIVERY

Sensor

Accessories have to be ordered separately

Manuals, Software & 3D Models available at: www.temposonics.com



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