

Data Sheet

T-Series – TH SSI Magnetostrictive Linear Position Sensors

- ATEX / UK Ex / IECEx / CEC / NEC / EAC Ex / CCC certified / Japanese approval / ClassNK approval
- Continuous operation under harsh industrial conditions
- Flameproof / Explosionproof / Increased safety



MEASURING TECHNOLOGY

The absolute, linear position sensors provided by Temposonics rely on the company's proprietary magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the beginning of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.

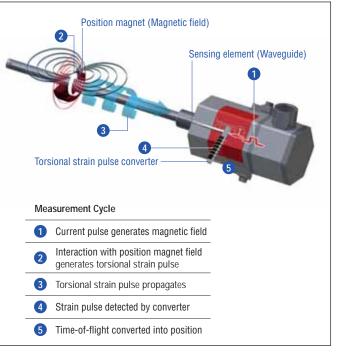


Fig. 1: Time-of-flight based magnetostrictive position sensing principle

TH SENSOR

Robust, non-contact and wear free, the Temposonics linear position sensors provide best durability and accurate position measurement solutions in harsh industrial environments. The position measurement accuracy is tightly controlled by the quality of the waveguide which is manufactured by Temposonics. The position magnet is mounted on the moving machine part and travels contactlessly over the sensor rod with the built-in waveguide.

The TH sensor is extremely robust and ideal for continuous operation under harsh industrial conditions. T-Series sensors are certified for hazardous areas in Zone 0/1, Zone 1, Zone 2, Zone 21 and Zone 22 for the European (ATEX), the English, Welsh and Scottish (UK Ex), the global (IECEx) market, the Eurasian Economic Union (EAC Ex), the South Korean (KCs), the Chinese (CCC) and the Japanese market. Further certifications are Class I, II, III, Division 1, Division 2 for Canada (CEC) and USA (NEC). The sensor electronics housing contains the active signal conditioning and a complete integrated electronics interface. The sensor rod is capable of withstanding high pressures such as those found in hydraulic cylinders. Furthermore the sensor is also suitable for petro chemical plants and caustic environments. In addition the sensor meets the ingress protection IP66/IP67/IP68 (100 m for 7 days)/IP69 and NEMA 4 (for sensor assembly in stainless steel 1.4305 (AISI 303)) or NEMA 4x (for sensor assembly in stainless steel 1.4404 (AISI 316L)).



Fig. 2: Typical application: Tank systems

TECHNICAL DATA

Output			
Interface	SSI (Synchronous Serial Interface) – differential signal in SSI standard (RS 422)		
Data format	Binary or gray, optional parity and error bit or temperature of sensor electronics		
Data length	832 bit		
Data transmission rate	70 kBaud ¹ 1 MBaud, depending on cable length: <u>Cable length < 3 m < 50 m < 100 m < 200 m < 400 m</u> Baud rate 1 MBd < 400 kBd < 300 kBd < 200 kBd < 100 kBd		
Measured value	Position, differentiation measurement, velocity, temperature of sensor electronics		
Measurement parameters			
Resolution	Position: 0.5 μm, 1 μm, 2 μm, 5 μm, 10 μm, 20 μm, 50 μm, 100 μm/ Velocity over 10 measured values: 0.1 mm/s (at 1 ms cycle time)		
Cycle time	Stroke length 300 mm 750 mm 1000 mm 2000 mm 5000 mm Measurement rate 3.7 kHz 3.0 kHz 2.3 kHz 1.2 kHz 0.5 kHz		
Linearity ²	< ±0.01 % F.S. (minimum ±40 µm)		
Repeatability	< ±0.001 % F.S. (minimum ±2.5 μm) typical		
Hysteresis	< 4 μm typical		
Temperature coefficient	< 15 ppm/K typical		
Operating conditions			
Operating temperature	-40+75 °C (-40+167 °F)		
Humidity	90 % relative humidity, no condensation		
Ingress protection	IP66/IP67/IP68 (100 m for 7 days)/IP69 and NEMA 4 (for sensor assembly in stainless steel 1.4305 (AISI 303)) or NEMA 4X (for sensor assembly in stainless steel 1.4404 (AISI 316L)) (if appropriate pipes, glands, etc. are connected properly)		
Shock test	100 g/6 ms according to IEC 60068-2-27		
Repeated shock events	160 g/2 ms according to IEC 60068-2-27 (for shock improved option A , see order code for Operating Voltage on page 13)		
Vibration test	15 g/102000 Hz according to IEC 60068-2-6 (excluding resonant frequencies)		
EMC test	Electromagnetic emission according to EN 61000-6-3 Electromagnetic immunity according to EN 61000-6-2 The sensor meets the requirements of the EU directives and is marked with CC The sensor meets the requirements of the UK-legislations and is marked with		
Operating pressure	350 bar static (5076 psi static)		
Magnet movement velocity ³	Any		
Design/Material			
Sensor electronics housing	Stainless steel 1.4305 (AISI 303); option: Stainless steel 1.4404 (AISI 316L)		
Flange	See "Table 1: TH rod sensor threaded flange type references" on page 7		
Sensor rod	Stainless steel 1.4306 (AISI 304L); option: Stainless steel 1.4404 (AISI 316L)		
Stroke length	257620 mm (1300 in.) (for shock improved option A , see order code on page 13: 253760 mm (1148 in.))		
Mechanical mounting			
Mounting position	Any		
Mounting instruction	Please consult the technical drawings and the operation manual (document number: <u>551902)</u>		

See next page for "Electrical connection"

1/ With standard one shot of 16 μs

2/ With position magnet # 201 542-2

3/ If there is contact between the moving magnet including the magnet holder and the sensor rod, make sure that the maximum speed of the moving magnet is < 1 m/s (Safety requirement due to ESD [Electro Static Discharge])

Temposonics® TH SSI Data Sheet

Electrical connection	
Connection type	T-Series terminal
Operating voltage	+24 VDC (-15/+20 %)
Ripple	\leq 0.28 V _{pp}
Current consumption	100 mA typical
Dielectric strength	700 VDC (DC ground to machine ground)
Polarity protection	Up to -30 VDC
Overvoltage protection	Up to 36 VDC

CERTIFICATIONS

Certification required	Version E	Version D	Version G	Version N
IECEx/ATEX (IECEx: Global market; ATEX: Europe)	Ex db eb IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex db IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex db IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	No hazardous area approval
UK Ex (England, Wales and Scotland)	Ex db eb IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex db IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex db IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C \leq Ta \leq 75 °C	No hazardous area approval
NEC (USA)			$\label{eq:starsest} \begin{array}{l} \textbf{Explosionproof} \\ \textbf{Class I Div. 1} \\ \textbf{Groups A, B, C, D T4} \\ \textbf{Class II/III Div. 1} \\ \textbf{Groups E, F, G T130°C} \\ \textbf{-40 °C} \leq \textbf{Ta} \leq 75 °C \end{array}$	No hazardous area approval
CEC (Canada)		—	Explosionproof Class I Div. 1 Groups B, C, D T4 Class II/III Div. 1 Groups E, F, G T130°C -40 °C \leq Ta \leq 75 °C Flameproof Class I Zone 0/1 Ex d IIC T4 Ga/Gb Class I Zone 0/1 Ex tb IIIC T130°C Db -40 °C \leq Ta \leq 75 °C	No hazardous area approval
EAC Ex (Eurasian Economic Union)	Ga/Gb Ex db eb IIC T4 X Ex tb IIIC T130°C Db X Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ga/Gb Ex db IIC T4 X Ex tb IIIC T130°C Db X Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ga/Gb Ex db IIC T4 X Ex tb IIIC T130°C Db X Zone 0/1, Zone 21 -40 °C \leq Ta \leq 75 °C	No hazardous area approval
Japanese approval	Ex d e IIC T4 Ga/Gb Ex t IIIC T130°C Db Zone 0/1, Zone 21 -40 °C \leq Ta \leq 75 °C	Ex d IIC T4 Ga/Gb Ex t IIIC T130°C Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex d IIC T4 Ga/Gb Ex t IIIC T130°C Db Zone 0/1, Zone 21 -40 °C \leq Ta \leq 75 °C	No hazardous area approval
CCC (China)	Ex d e IIC T4 Gb Ex tD A21 IP66/67 T130°C Zone 1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex d IIC T4 Gb Ex tD A21 IP66/67 T130°C Zone 1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex d IIC T4 Gb Ex tD A21 IP66/67 T130°C Zone 1, Zone 21 −40 °C ≤ Ta ≤ 75 °C	No hazardous area approval

Fig. 3: Certifications

TECHNICAL DRAWING

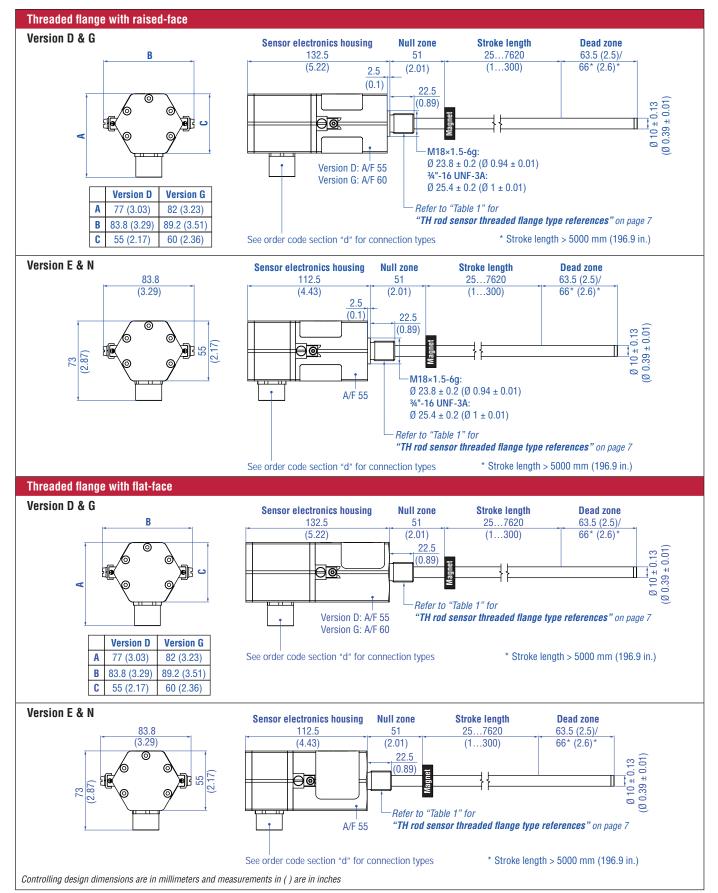


Fig. 4: Temposonics® TH with ring magnet

CONNECTION OPTIONS

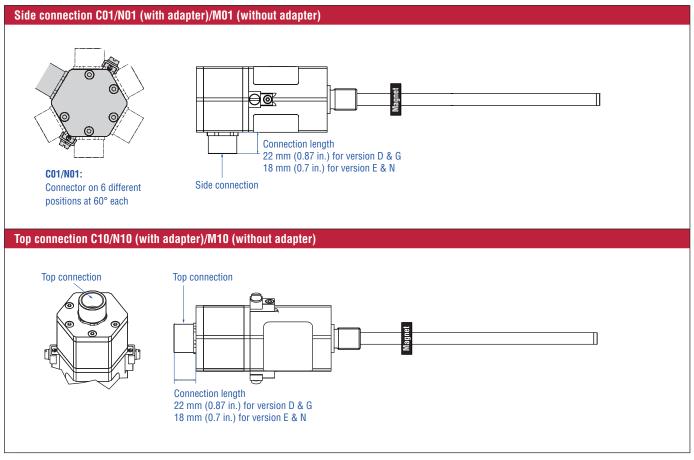


Fig. 5: Temposonics® TH connection options

Threaded flange type	Description	Threaded flange
F	Threaded flange with flat-face Stainless steel 1.4404 (AISI 316L)	3⁄4"-16 UNF-3A
G	Threaded flange with raised-face Stainless steel 1.4404 (AISI 316L)	3⁄4"-16 UNF-3A
М	Threaded flange with flat-face Stainless steel 1.4305 (AISI 303)	M18×1.5-6g
N	Threaded flange with raised-face Stainless steel 1.4305 (AISI 303)	M18×1.5-6g
S	Threaded flange with flat-face Stainless steel 1.4305 (AISI 303)	3⁄4"-16 UNF-3A
т	Threaded flange with raised-face Stainless steel 1.4305 (AISI 303)	3⁄4"-16 UNF-3A
W	Threaded flange with flat-face Stainless steel 1.4404 (AISI 316L)	M18×1.5-6g

Table 1: TH rod sensor threaded flange type references

ZONE CLASSIFICATION

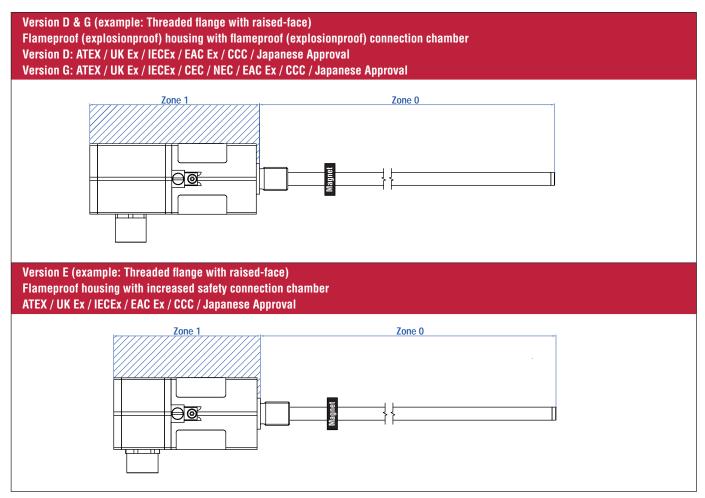


Fig. 6: Temposonics® TH Zone classification

NOTICE

Seal sensor according to ingress protection IP67 between Zone 0 and Zone 1.

CONNECTOR WIRING

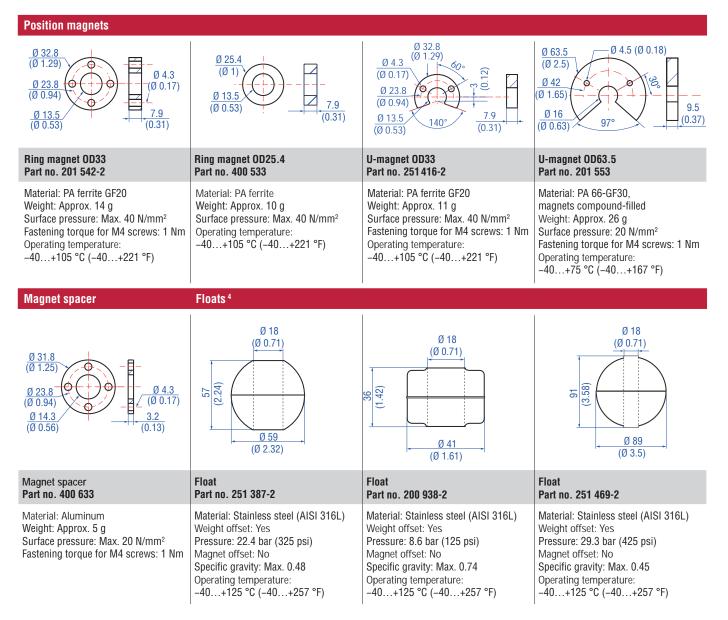
Version D & G suitable for connection types: C01, C10, N01, N10					
Signal + power s	Signal + power supply				
Terminal		Pin	Function		
		1	Data (-)		
		2	Data (+)		
		3	Clock (+)		
		4	Clock (-)		
v		5	+24 VDC (-15/+20 %)		
60		6	DC Ground (0 V)		
		7	Cable shield		

Fig. 7: TH (version D & G) wiring diagram (2.5 mm² conductor)

Version E & N suitable for connection types: C01, C10, M01, M10, N01, N10				
Signal + power supply				
Terminal	Pin	Function		
	1	Data (–)		
	2	Data (+)		
	3	Clock (+)		
4 0	4	Clock (-)		
	5	+24 VDC (-15/+20 %)		
	6	DC Ground (0 V)		
	7	Cable shield		

Fig. 8: TH (version E & N) wiring diagram (1.5 mm² conductor)

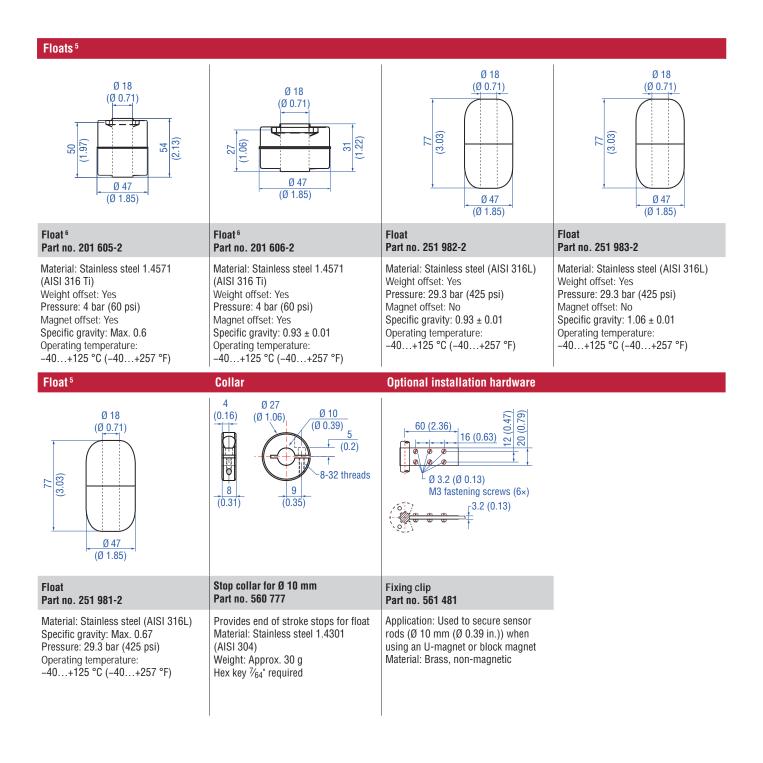
FREQUENTLY ORDERED ACCESSORIES – Additional options available in our Accessories Guide 🗍 551444



Controlling design dimensions are in millimeters and measurements in () are in inches

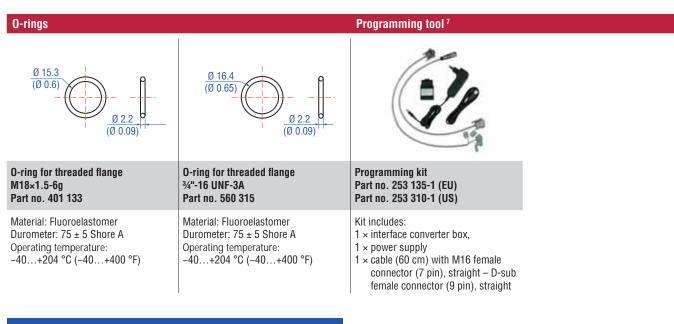
- 4/ Be sure that the float specific gravity is at least 0.05 less than that of the measured liquid as a safety margin at ambient temperature
 - For interface measurement: A minimum of 0.05 specific gravity differential is required between the upper and lower liquids
- \bullet When the magnet is not shown, the magnet is positioned at the center line of float

 An offset weight is installed in the float to bias or tilt the float installed on the sensor tube. So the float remains in contact with the sensor tube at all times and guarantees permanent potential equalization of the float. The offset is required for installations that must conform to hazardous location standards



Controlling design dimensions are in millimeters and measurements in () are in inches

- ${\bf 5}/~{\bf \bullet}$ Be sure that the float specific gravity is at least 0.05 less than that of the measured liquid as a safety margin at ambient temperature
 - For interface measurement: A minimum of 0.05 specific gravity differential is required between the upper and lower liquids
 - When the magnet is not shown, the magnet is positioned at the center line of float
- An offset weight is installed in the float to bias or tilt the float installed on the sensor tube. So the float remains in contact with the sensor tube at all times and guarantees permanent potential equalization of the float. The offset is required for installations that must conform to hazardous location standards
- ${\bf 6}/~$ Standard float that can be expedited

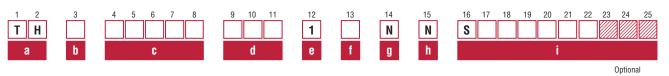


Manuals, Software & 3D Models available at: www.temposonics.com

Controlling design dimensions are in millimeters and measurements in () are in inches

7/ The programming tool is not approved for use in hazardous environments

ORDER CODE



	Sen	sor	mou	lel			
T							
b	b Design						
	closu						
					-	terial stainless	steel 1.4305 306 (AISI 304L)
M						ce (M18×1.5-6g	. ,
N				-		-face (M18×1.5-	, ,
S				-		ce (¾"-16 UNF-3	•,
Т				-		-face (¾"-16 UN	,
	closu			-			
					housing ma	terial stainless	steel 1.4404
(Al	SI 31	6L)	and	rod	material st	ainless steel 1.	4404 (AISI 316L)
F	Thre	ead	ed fla	ange	with flat-fac	ce (¾"-16 UNF-3	BA)
G	Thre	ead	ed fla	ange	with raised	-face (¾"-16 UN	F-3A)
W	Thre	ead	ed fla	ange	with flat-fac	ce (M18×1.5-6g)
C		_	leng	_	0005 700	0	
X					0025762		
	_	_	_	_	gth (mm)	Ordering ste	eps
_	25					5 mm	
	00					10 mm	
	50					25 mm	
	00	250	u mi	n		FO	
	25005000 mm				50 mm		
						100 mm	
500	00	762	0 mi	n	001.0	100 mm 250 mm	
500 X	00 [*]	762 X	0 mi . X	n U		100 mm 250 mm 0.0 in.	
500 X Sta	00 X ndar	762 X d st	0 mr . X roke	n U	001.0300 gth (in.)	100 mm 250 mm 0.0 in. Ordering ste	ps
500 X Sta	00 [*] X	762 X d st 20 i	0 mr . X roke n.	n U		100 mm 250 mm).0 in. Ordering ste 0.2 in.	ibz
500 X Sta	00 X ndar 1 1 0 1	762 X d st 20 i 30 i	0 mr . X roke n. n.	n U		100 mm 250 mm 0.0 in. Ordering ste 0.2 in. 0.4 in.	ps
500 X Sta 20 30	00 X Indar 1 1 0 1	762 X d st 20 i 30 i 40 i	0 mr . X roke n. n. n.	n U		100 mm 250 mm 0.0 in. Ordering ste 0.2 in. 0.4 in. 1.0 in.	:ps
500 X Sta 20 30 40	001	762 X d st 20 i 30 i 40 i	0 mr . X roke n. n. n.	n U		100 mm 250 mm 0.0 in. Ordering ste 0.2 in. 0.4 in. 1.0 in. 2.0 in.	ps
500 X Sta 1 20 30 40 100	00 ¹ x 1 1 0 1 0 1 01	762 X d st 20 i 30 i 40 i 00 i	0 mi . X roke n. n. n. n.	n U		100 mm 250 mm 0.0 in. Ordering ste 0.2 in. 0.4 in. 1.0 in. 2.0 in. 4.0 in.	:b2
500 X Sta 1 20 30 40 100 200	00 X ndar 1 2 0 2 0 2 0 2 0 2 0 3	762 X d st 20 i 30 i 40 i 00 i 00 i	0 mi . X n. n. n. n. n.	n U Ien		100 mm 250 mm 0.0 in. Ordering ste 0.2 in. 0.4 in. 1.0 in. 2.0 in. 4.0 in. 10.0 in.	ps

	0			,
must be encoded	l in 5	mm/0.1	in.	increments.

d	Co	Connection type						
C	0	1	Side connection with thread ½"-14 NPT (All versions)					
C	1	0	Top connection with thread ½"-14 NPT (All versions)					
М	0	1	Side connection with thread M16×1.5-6H (Version E & N)					
М	1	0	Top connection with thread M16×1.5-6H (Version E & N)					
N	0	1	Side connection with thread M20×1.5-6H (All versions)					
N	1	0	Top connection with thread M20×1.5-6H (All versions)					

Operating voltage

1	+24 VDC	(-15/+20	%)
---	---------	----------	----

A +24 VDC (-15/+20 %) includes shock improved option stroke length 25...3760 mm (1...148 in.)

f	Version (see "Certifications" on page 5 for further information)
D	Ex db and Ex tb (A/F 55)
Ε	Ex db eb and Ex tb (A/F 55)
G	Ex db and Ex tb (A/F 60) <u>US & CA approval:</u> Explosionproof (XP) (Note: Group A is not available for Canada)
N	Not approved
g	Functional safety type
Ν	Not approved

h Additional option type

N None

i See next page

i	Output	i	Output (continued)		
	17) (18) (19) (20) (21) (22) (23) (24) (25)		easurement contents (optional: Box no. 23)		
	Synchronous Serial Interface	Note: Choose "9" in box no. 21 and 22			
Da	ta length (box no. 17)	1	Position measurement		
1	25 bit	2	Differentiation measurement ⁸		
2	24 bit	3	Velocity measurement		
3	26 bit	4	Position measurement + temperature measurement		
Ou	tput format (box no. 18)		(only with data length = 24 bit)		
В	Binary	5	Differentiation measurement ⁸ + temperature measurement		
G	Gray		(only with data length = 24 bit)		
Re	solution (box no. 19)	6	Velocity measurement + temperature measurement		
1	0.005 mm		(only with data length = 24 bit)		
2	0.01 mm		rection and sync. mode (optional: Box no. 24) ite: Choose "9" in box no. 21 and 22		
3	0.05 mm	1	Measuring direction forward, asynchronous mode		
4	0.1 mm	2	Measuring direction forward, synchronous mode 1		
5	0.02 mm	3	Measuring direction forward, synchronous mode 1		
6	0.002 mm	4	Measuring direction forward, synchronous mode 2 Measuring direction forward, synchronous mode 3		
8	0.001 mm	4			
9	0.0005 mm		Measuring direction reverse, asynchronous mode		
Fil	tering performance (box no. 20)	6	Measuring direction reverse, synchronous mode 1		
Α	No filter + error delay (4 cycles)	7	Measuring direction reverse, synchronous mode 2		
C	No filter + error delay (8 cycles)	8	Measuring direction reverse, synchronous mode 3		
1	Standard (no filters)		agnostics (optional: Box no. 25) ite: Choose "9" in box no. 21 and 22		
8	Noise reduction filter (8 measurements)	0	No further options		
D	No filter + error delay (10 cycles)	2	Additional alarm bit + parity even bit		
G	Noise reduction filter (8 measurements) + error delay (10 cycles)	_	(not available for temperature output, only with data length = 24 bit)		
K	Peak reduction filter (8 measurements)				
N	Peak reduction filter (8 measurements) + error delay (10 cycles)				
Sig	inal options (box no. 21, 22)		DTICE		
0	0 Measuring direction forward, asynchronous mode		e magnets of the same type (e.g. 2 ring magnets with part no. 1 542-2) for differentiation measurement.		
0	1 Measuring direction reverse, asynchronous mode	20			

DELIVERY

Sensor

Accessories have to be ordered separately

Manuals, Software & 3D Models available at: www.temposonics.com

2 Measuring direction forward, synchronous mode 1 **0 5** Measuring direction forward, asynchronous mode, bit 25 = alarm, bit 26 = parity even

9 9 Write "9" in box no. 21 and 22 for using further combinations in boxes 23, 24, 25

0



UNITED STATES Temposonics, LLC Americas & APAC Region	St LC Cary, N.C. 27513 551950 Revision Region Phone: +1 919 677-0100 551950 Revision	Document Part Number 551950 Revision D (EN) 04/2022
Temposonics GmbH & Co. KG	Auf dem Schüffel 9 58513 Lüdenscheid Phone: +49 2351 9587-0 E-mail: info.de@temposonics.com	CE ERTIFIED
	Phone: +39 030 988 3819 E-mail: info.it@temposonics.com	
	Phone: +33 6 14 060 728 E-mail: info.fr@temposonics.com	
	Phone: +44 79 44 15 03 00 E-mail: info.uk@temposonics.com	
	Phone: + 46 70 29 91 281 E-mail: info.sca@temposonics.com	
	Phone: +86 21 2415 1000 / 2415 1001 E-mail: info.cn@temposonics.com	
	Phone: +81 3 6416 1063 E-mail: info.jp@temposonics.com	

temposonics.com

© 2022 Temposonics, LLC – all rights reserved. Temposonics, LLC and Temposonics GmbH & Co. KG are subsidiaries of Amphenol Corporation. Except for any third party marks for which attribution is provided herein, the company names and product names used in this document may be the registered trademarks or unregistered trademarks of Temposonics, LLC or Temposonics GmbH & Co. KG. Detailed trademark ownership information is available at www.temposonics.com/trademarkownership.